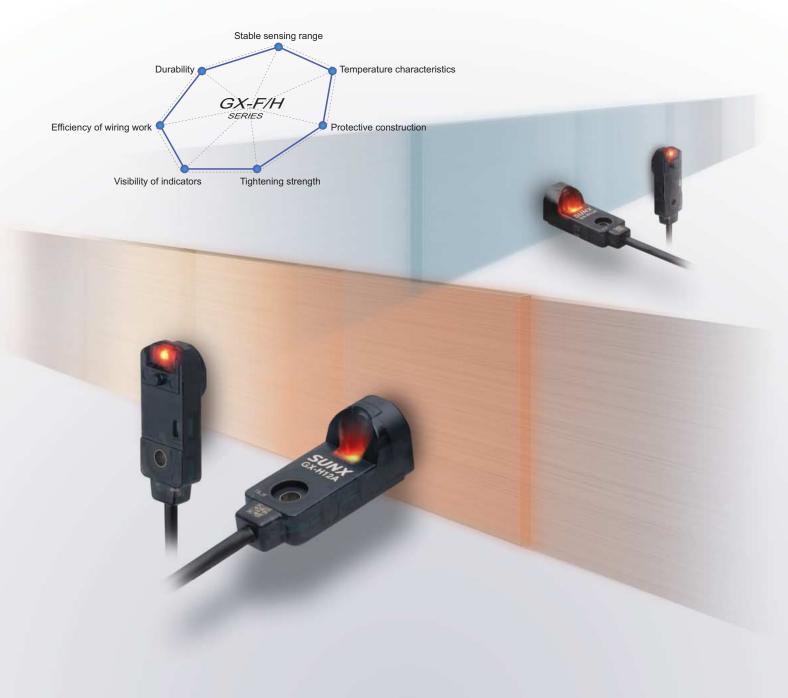


GX-F/HSERIES

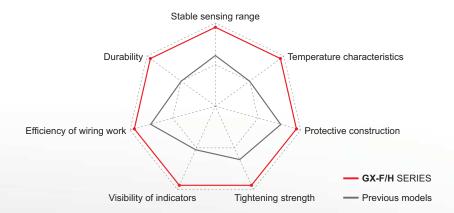


In response to the requirements of our customers

Industry No. 1* in stable sensing



^{*} Based on research conducted by SUNX as of August 2007 among equivalent rectangular inductive proximity sensors.



Use with confidence at any time and anywhere

Have you ever thought that sensing was simple, but then when you tried to use an rectangular inductive proximity sensor, the sensing was not stable? It is because SUNX is the leading manufacturer of inductive proximity sensors that we have been able to accumulate our sensor technology to develop high-precision inductive proximity sensors that can be used at any time and anywhere.

The requirements of our customers have been accommodated by basic performance which is not to be found with other manufacturers.



The industry No. 1* in accommodating to customer requirements in basic performance

* Based on research conducted by SUNX as of August 2007 among equivalent rectangular inductive proximity sensors.

Customer requirements	Answer of GX-F/H series	
We're frustrated because sensing results weren't stable. 1 And the screw mounting method makes it difficult to adjust the sensor position.	>> Industry No. 1 in stable sensing	P.3 Maximum operation distance variation: 0.4 mm 0.016 in or less Maximum operation distance: 2.5 mm 0.098 in ± 8 % (2.3 to 2.7 mm 0.091 to 0.106 in)
When the sensing position changes because of temperature variations during the morning, afternoon and nighttime, fine adjustments become very difficult to make.	>> Industry No. 1 in temperature characteristics	P.4 23 °C 73 °F 74 °F 75
We want sensors that are good at withstanding vibration and shocks!	>> Industry No. 1 in durability	P.5
Are the sensors really safe to be used in places where water or oil will get on them?	>> Industry No. 1 in protective construction	P.5
We'd really like to have sensors that let you see the operating status at a glance.	>> Bright and easy-to-see indicators	P.5
If you tighten the screws too tightly, it will damage the sensors.	>> Improved tightening strength	P.6
There are too many thin wires which are very difficult to work with!	>> Greater efficiency in wiring work	P.6

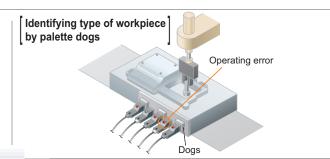
Customer requirements



We're frustrated because sensing results weren't stable. And the screw mounting method makes it difficult to adjust the sensor position.

<Have you ever had this experience?>

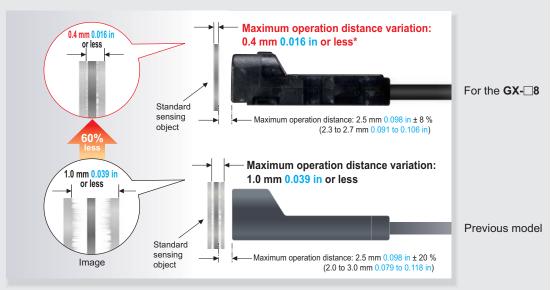
- The positions of rectangular inductive proximity sensors which are installed using screws cannot be adjusted, and so they have been designed with as short sensing ranges as possible to minimize variations caused by the sensing range.
- The sensor used as a replacement for maintenance has a longer sensing range, so that not only the dog but also the base was detected, meaning that position adjustment is necessary.



Answer of GX-F/H series

Industry No.1

Stable sensing! Variation at the maximum operation distance is within ±8 %



Thorough adjustment and control of sensing sensitivity greatly reduces individual sensor differences and variations. The work of adjusting sensor positions when using multiple sensors and when sensors have been replaced has become much easier.

* Not including temperature characteristics.
GX-□12 has a variation of 0.64 mm
0.025 in or less for a maximum operation distance of 4 mm 0.157 in



Answer of GX-F/H series

The longest stable sensing range in the industry gives you much greater flexibility.



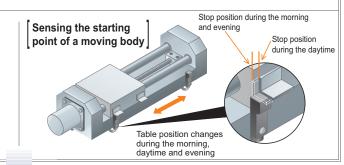
Customer requirements



When the sensing position changes because of temperature variations during the morning, afternoon and nighttime, fine adjustments become very difficult to make.

<Have you ever had this experience?>

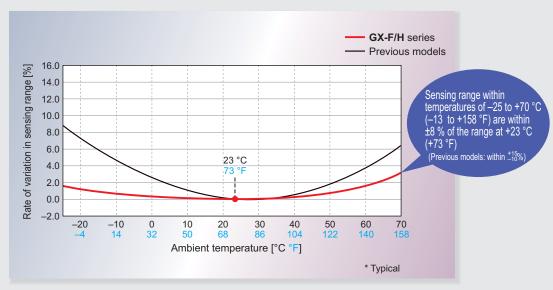
- Temperature differences between morning and nighttime or as a result of seasonal changes cause slight shifts in the sensing position.
- © Every time when the equipment is moved to a place with different weather conditions, readjustments are necessary.



Answer of GX-F/H series

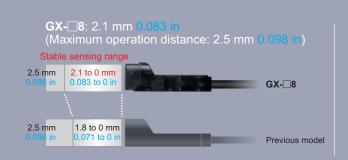
Industry No.1

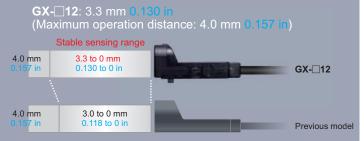
Stable sensing! Temperature characteristics vary within ±8 %



Components such as the sensor coil and core and product design have been totally revised to provide excellent temperature characteristics. Stable sensing can be obtained regardless of the time of the day or the yearly seasons.







Customer requirements

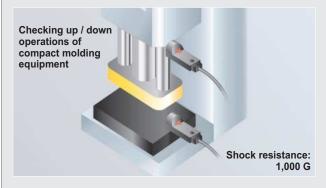


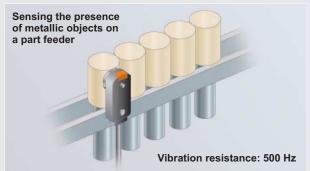
We want sensors that are good at withstanding vibration and shocks!

Answer of GX-F/H series

Industry No.1

10 times the durability! (Compared to previous models)





The new integrated construction method used provides shock resistance of $10,000 \text{ m/s}^2$ (approx. 1,000 G in X, Y and Z directions for three times each), and vibration resistance which clears durability tests of between 10 and 500 Hz (3 mm 0.118 in amplitude in X, Y and Z directions for 2 hours each). In addition, resistance to impulse noize is approx. three times greater than for previous models.



Customer requirements



Are the sensors really safe to be used in places where water or oil will get on them?

Answer of GX-F/H series

Industry No.1

Highly resistant to water or oil! IP68g* protective construction



The new integrated construction method used improves environmental resistance performance.

The IP68g prevents damage to the sensor by stopping water and oil from getting inside.

* For details, refer to the "SPECIFICATIONS" (p.8~)



Customer



We'd really like to have sensors that let you see the operating status at a glance.

Answer of GX-F/H series









GX-F







A prism with a wide field of view has been developed. This has greatly improved the visibility of the operation indicators.







If you tighten the screws too tightly, it will damage the sensors.



A metal sleeve has been inserted!

* Maximum tightening torque for M3 screw.

It is possible to tighten up to

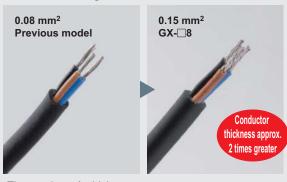
Customer requirements



There are too many thin wires which are very difficult to work with!

Answer of GX-F/H series

Conductor thickness doubled to make wiring much easier! (GX-\subseteq 8 only)

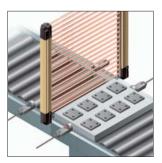


The conductor's thickness was doubled for the **GX-**—8. This makes it easier to handle and perform crimping work on the cables. In addition, the tensile strength of the crimping area has become higher.



Applications

0.7 N·m *.



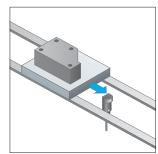
Muting control of light curtains



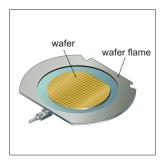
Detecting cam position



Detecting rolling coins



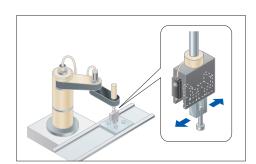
Positioning metal pallets



Detecting wafer flame



Positioning processing equipment



Checking robot finger chucks

ORDER GUIDE

GX-8 type

Ту	/pe	Appearance (mm in)	Sensing range (Note 1)	Model No. (Note 2)	Output	Output operation
	ng	~		GX-F8A		Normally open
	sensing	7.4 0.291		GX-F8AI		Normany open
=	Front s	8 0.315 0.906		GX-F8B		Normally closed
NPN output	Ţ.			GX-F8BI	NPN open-collector	Normally closed
PN	g	~ 🔿		GX-H8A	transistor	Normally on an
Z	nsin	sensing		0.323 Maximum GX-H8AI operation distance GX-H8B	GX-H8AI	Normally open
	Top se	25	operation distance			Normally closed
	Ĕ	8 0.315 0.984 2.5 mm 0.098 in	2.5 mm 0.098 in	GX-H8BI	H8BI	
	βL	- 4	(0 to 2.1 mm 0 to 0.083 in)	GX-F8A-P		Name
	sensing	7.4 0.291		GX-F8AI-P		Normally open
+=	Front s	23	GX-F8BI-P GX-H8A-P GX-H8AI-P RNP open-collected transistor		No	
PNP output	Fr	0.906		PNP open-collector	Normally closed	
NP o	D	\(\sigma\)		GX-H8A-P		
₫.	PN			GX-H8AI-P		Normally open
	Top se	8.2 0.323		GX-H8B-P		
	1	8 0.315 0.984		GX-H8BI-P		Normally closed

Notes: 1) The maximum operation distance stands for the maximum distance for which the sensor can detect the standard sensing object.

The stable sensing range stands for the sensing range for which the sensor can stably detect the standard sensing object even if there is an ambient temperature drift and/or supply voltage fluctuation.

2) "I" in the model No. indicates a different frequency type.

GX-12 type

Ту	/ре	Appearance (mm in)	Sensing range (Note 1)	Model No. (Note 2)	Output	Output operation		
	ng			GX-F12A		Normally open		
	sensing	7.1 0.280		GX-F12AI		Normany open		
=	Fronts	27.8		GX-F12B		Normally closed		
NPN output	F	0.472 < 1.094		GX-F12BI	NPN open-collector	Normany closed		
PN	g			GX-H12A	transistor	Normally open		
Z	ensir	12 0.472	12 0.472 Maximum operation distance 12 0.472 4.0 mm 0.157 in	Maximum operation distance GX-H12AI GX-H12B	GX-H12AI		Normally open	
	Top se	27.4			Normally along			
	Ĕ	12 0.472		GX-H12BI		Normally closed		
	βL		(0 to 3.3 mm 0 to 0.130 in)	GX-F12A-P		Normally on an		
	sensing	7.1 0.280		GX-F12AI-P		Normally open		
.	Front s	27.8	Stable sensing range	GX-F12B-P		No see all set a see al		
PNP output	Fre	0.472	0.472 < 1.094 GX-F12BI-P	PNP open-collector	Normally closed			
NP o	б	. D	50			GX-H12A-P	transistor	
Δ.	sensing	12 0.472		GX-H12AI-P		Normally open		
	Top se	27.4 12 0.472 1.079		GX-H12B-P		Name allocated and		
	T	12 0.472		GX-H12BI-P		Normally closed		

Notes: 1) The maximum operation distance stands for the maximum distance for which the sensor can detect the standard sensing object.

The stable sensing range stands for the sensing range for which the sensor can stably detect the standard sensing object even if there is an ambient temperature drift and/or supply voltage fluctuation.

2) "I" in the model No. indicates a different frequency type.

OPTIONS

Designation	Model No.	Description
Sensor mounting bracket MS-GXL8-4		Mounting bracket for GX-8 type

Sensor mounting bracket

• MS-GXL8-4



1 pc. each of M3 (length: 12 mm 0.472 in) truss head screw, nut, spring washer and plain washer is attached.

SPECIFICATIONS

GX-8 type

Туре			NPN (output	PNP	output
		Front sensing Top sensing	GX-F8A(I)	GX-F8B(I)	GX-F8A(I)-P	GX-F8B(I)-P
Item	1 \	Top sensing	GX-H8A(I)	GX-H8B(I)	GX-H8A(I)-P	GX-H8B(I)-P
Max.	opera	tion distance (Note 3)	2.5 mm 0.098 in ± 8 %			
Stable sensing range (Note 3)				0 to 2.1 mm	0 to 0.083 in	
Standard sensing object Iron sheet 15 × 15 × t 1 mm 0.591 × 0.591 × t 0.039 in			1 0.591 × 0.591 × t 0.039 in			
Hysteresis			:	20 % or less of operation distance	ce (with standard sensing object))
Repe	eatabil	lity	Along	sensing axis, perpendicular to s	ensing axis: 0.04 mm 0.0016 in	or less
Supp	oly vol	tage		12 to 24 V DC ⁺¹⁰ ₋₁₅ %	Ripple P-P 10 % or less	
Curr	ent co	nsumption		15 mA	or less	
Output			Residual voltage: 1 V or le	or less (between output and 0 V)	PNP open-collector transistor	
	Outp	ut operation	Normally open	Normally closed	Normally open	Normally closed
Max. response frequency		onse frequency	500 Hz			
Operation indicator		indicator	Orange LED (lights up when the output is ON)			
φ	Prote	ection	IP68 (IEC), IP68g (JEM) (Note 4, 5)			
stanc	Ambi	ent temperature	-25 to +70 °C −13 to +158 °F, Storage: −40 to +85 °C −40 to +185 °F			
Environmental resistance	Ambi	ent humidity	45 to 85 % RH, Storage: 35 to 95 % RH			
ental	Volta	ge withstandability	1,000 V AC for one min. between all supply terminals connected together and enclosure			
onme	Insul	ation resistance	50 M Ω , or more, with 500 V DC megger between all supply terminals connected together and enclosure			
Envir	Vibra	tion resistance	10 to 500 Hz frequency, 3 mm 0.118 in amplitude in X, Y and Z directions for two hours each			
Shock resistance 10,000 m/s² acceleration (1,000 G approx.) in X, Y and Z directions for three times ea			times each			
Sensing range Temperature characteristics Over ambient temperature range –25 to +70 °C –13 to +158 °F		+158 °F: Within ±8 % of sensing range at +23 °C +73 °F				
variation Voltage characteristics Within ±2 % for $^{+10}_{-15}$ % fluctuation of the supply voltage		uation of the supply voltage				
Material Enclosure: PBT, Indicator part: Polyester		icator part: Polyester				
Cabl	е		0.15 r	nm ² 3-core oil, heat and cold res	sistant cabtyre cable, 1 m 3.281	ft long
Cabl	e exte	nsion	Extensi	on up to total 100 m 328.084 ft i	s possible with 0.3 mm ² , or more	e, cable.
Net	weight		F	Front sensing type: 15 g approx.	, Top sensing type: 20 g approx.	

- Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +23 °C +73 °F.

 2) "I" in the model No. indicates a different frequency type.

 - 3) The maximum operation distance stands for the maximum distance for which the sensor can detect the standard sensing object. The stable sensing range stands for the sensing range for which the sensor can stably detect the standard sensing object even if there is an ambient temperature drift and/or supply voltage fluctuation.
 - 4) SUNX's IP68 test method
 - ① Immerse at 0 m below 0 °C +32 °F water surface and leave for 30 min. Then, immerse at 0 m below +70 °C +158 °F water surface and leave for 30 min. ② Regard the heat shock test in ① as one cycle and perform 20 cycles.

 - 3 Leave in water at a depth of 1 m 3.281 ft in water for 500 hours.
 - 4 After tests 1 to 3, insulation resistance, voltage withstandability, current consumption, and sensing ranges must meet the standard values.
 - 5) If using the sensor in an environment where cutting oil droplets splatter, the sensor may deteriorate due to added substances in the oil.

SPECIFICATIONS

GX-12 type

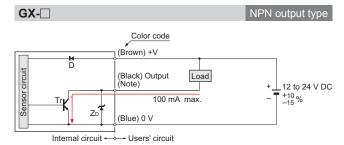
Туре			NPN (output	PNP output	
		Front sensing	GX-F12A(I)	GX-F12B(I)	GX-F12A(I)-P	GX-F12B(I)-P
Iten	n \	Tront sensing Top sensing	GX-H12A(I)	GX-H12B(I)	GX-H12A(I)-P	GX-H12B(I)-P
Max	. opera	tion distance (Note 3)	4.0 mm 0.157 in ± 8 %			
Stat	ole sen	sing range (Note 3)		0 to 3.3 mm	0 to 0.130 in	
Star	ndard s	sensing object		Iron sheet 0 × 20 × t 1 mm	0.787 × 0.787 × t 0.039 in	
Hys	teresis		:	20 % or less of operation distance	ce (with standard sensing object)
Rep	eatabil	lity	Along	sensing axis, perpendicular to s	ensing axis: 0.04 mm 0.0016 in	or less
Sup	ply vol	tage		12 to 24 V DC ⁺¹⁰ ₋₁₅ %	Ripple P-P 10 % or less	
Curr	ent co	nsumption		15 mA	or less	
Output			Residual voltage: 1 V or le	or less (between output and 0 V)	PNP open-collector transistor • Maximum source current: 100 mA • Applied voltage: 30 V DC or less (between output and • Residual voltage: 1 V or less (at 100 mA source current) 0.4 V or less (at 16 mA source current)	
	Outp	ut operation	Normally open	Normally closed	Normally open	Normally closed
Max	. respo	onse frequency	500 Hz			
Ope	ration	indicator	Orange LED (lights up when the output is ON)			
ø	Prote	ection	IP68 (IEC), IP68g (JEM) (Note 4, 5)			
stanc	Ambi	ent temperature	-25 to +70 °C −13 to +158 °F, Storage: −40 to +85 °C −40 to +185 °F			
Environmental resistance	Ambi	ent humidity	45 to 85 % RH, Storage: 35 to 95 % RH			
ental	Volta	ge withstandability	1,000 V AC for one min. between all supply terminals connected together and enclosure			
onme	Insul	ation resistance	$50\ M\Omega,$ or more, with $500\ V$ DC megger between all supply terminals connected together and enclosure			
Envir	Vibra	tion resistance	10 to 500 Hz frequency, 3 mm 0.118 in amplitude in X, Y and Z directions for two hours each			
ш_	Shoc	k resistance	10,000 m/s ²	acceleration (1,000 G approx.)	in X, Y and Z directions for three	e times each
Sensing Temperature characteristics		Temperature characteristics	Over ambient temperature range –25 to +70 °C –13 to +158 °F: Within ±8 % of sensing range at +23 °C +73 °F			
variation Voltage characteristics		Voltage characteristics	Within ± 2 % for $^{+10}_{-15}$ % fluctuation of the supply voltage			
Mate	erial		Enclosure: PBT, Indicator part: Polyester			
Cab	le		0.15 mm² 3-core oil, heat and cold resistant cabtyre cable, 1 m 3.281 ft long			
Cab	le exte	ension	Extension up to total 100 m 328.084 ft is possible with 0.3 mm², or more, cable.			
Net	weight		Ī	Front sensing type: 20 g approx.	, Top sensing type: 20 g approx.	
	43.34	/horo magairament o		d procingly, the conditions would		5 . 00 00 . TO 0F

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +23 °C +73 °F.

- 2) "I" in the model No. indicates a different frequency type.
- 3) The maximum operation distance stands for the maximum distance for which the sensor can detect the standard sensing object.

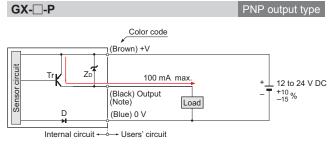
 The stable sensing range stands for the sensing range for which the sensor can stably detect the standard sensing object even if there is an ambient temperature drift and/or supply voltage fluctuation.
- 4) SUNX's IP68 test method
 - ① Immerse at 0 m below 0 °C +32 °F water surface and leave for 30 min. Then, immerse at 0 m below +70 °C +158 °F water surface and leave for 30 min.
 - ② Regard the heat shock test in ① as one cycle and perform 20 cycles.
 - 3 Leave in water at a depth of 1 m 3.281 ft in water for 500 hours.
- 4 After tests 1 to 3, insulation resistance, voltage withstandability, current consumption, and sensing ranges must meet the standard values.
- 5) If using the sensor in an environment where cutting oil droplets splatter, the sensor may deteriorate due to added substances in the oil.

I/O CIRCUIT DIAGRAMS



Note: The output does not incorporate a short-circuit protection circuit. Do not connect it directly to a power supply or a capacitive load.

Symbols ... D : Reverse supply polarity protection diode $$Z_{\text{\tiny D}}$$: Surge absorption zener diode Tr: NPN output transistor



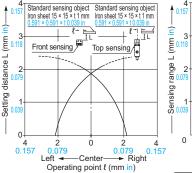
Note: The output does not incorporate a short-circuit protection circuit. Do not connect it directly to a power supply or a capacitive load.

Symbols ... D : Reverse supply polarity protection diode $Z_{\text{\scriptsize D}}\text{:}$ Surge absorption zener diode Tr: PNP output transistor

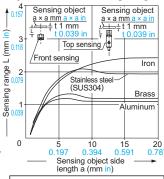
SENSING CHARACTERISTICS (TYPICAL)

GX-8 type

Sensing field



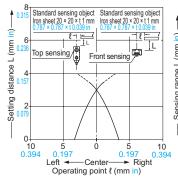
Correlation between sensing object size and sensing range



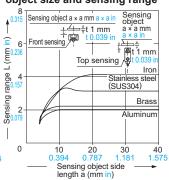
As the sensing object size becomes smaller than the standard size (iron sheet $15 \times 15 \times 11 \times 1000$ km s. 1000×10000 km s. 1000×1000 km s

GX-12 type

Sensing field



Correlation between sensing object size and sensing range



As the sensing object size becomes smaller than the standard size (iron sheet $20 \times 20 \times 11 \times 1000$ mm $0.787 \times 0.787 \times 10.039$ in), the sensing range shortens as shown in the left figure.

PRECAUTIONS FOR PROPER USE



- Never use this product as a sensing device for personnel protection.
- In case of using sensing devices for personnel protection, use products which meet laws and standards, such as OSHA, ANSI or IEC etc., for personnel protection applicable in each region or country.

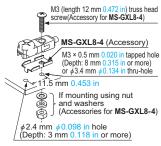
Mounting

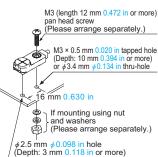
GX-8 type

Make sure to use a M3 (length: 12 mm 0.472 in or more) truss head screw. The tightening torque should be 0.7 N·m or less. (Do not use a flat head screw or a pan head screw.)



- The tightening torque should be 0.7 N·m or less.
- To mount the sensor with a nut, the mouting hole diameter should be ϕ 3.4 mm ϕ 0.134 in. Further, the hole in which the boss is inserted should be ϕ 2.5 mm ϕ 0.098 in and 3 mm 0.118 in, or more, deep.

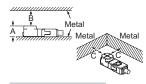




Influence of surrounding metal

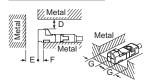
 When there is a metal near the sensor, keep the minimum separation distance specified below.

Front sensing type



	GX-F8 type	GX-F12 type
Α	7.4 mm 0.291 in	7.1 mm 0.280 in
В	8 mm 0.315 in	20 mm 0.787 in
С	3 mm 0.118 in	7 mm 0.276 in

Top sensing type



		GX-H8 type	GX-H12 type
	О	4 mm 0.157 in	7 mm 0.276 in
Ī	Е	10 mm 0.394 in	20 mm 0.787 in
	F	3 mm 0.118 in	3 mm 0.118 in
	G	3 mm 0.118 in	3 mm 0.118 in

Mutual interference prevention

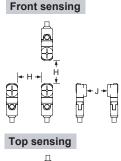
 When two or more sensors are installed in parallel or face to face, keep the minimum separation distance specified below to avoid mutual interference.

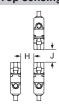
	Н	J	
GX-F8□	Between "I" type and non "I" type	0 mm (Note 2)	15 mm 0.591 in
GX-H8□	Between two "I" types or two non "I" types	20 mm 0.787 in	35 mm 1.378 in
GX-F12□	Between "I" type and non "I" type	0 mm (Note 2)	25 mm 0.984 in
GX-H12□	Between two "I" types or two non "I" types	25 mm 0.984 in	50 mm 1.969 in

Notes: 1) "I" in the model No. specifies

the different frequency type.
2) Close mounting is possible for up to two sensors.
When mounting three sensors or more at an equal spacing, align the model with "I" and the model without "I" alternately. The minimum value of dimension "H" should be as given below.

GX-8 type: 6 mm 0.236 in
GX-12 type: 6.5 mm 0.256 in





Sensing range

The sensing range is specified for the standard sensing object.
With a non-ferrous metal, the sensing range is obtained by
multiplying with the correction coefficient specified below.
Further, the sensing range also changes if the sensing object is
smaller than the standard sensing object or if the sensing object
is plated.

Correction coefficient

Model No. Metal	GX-8 type	GX-12 type	
	_	4	
Iron	1	1	
Stainless steel (SUS304)	0.76 approx.	0.79 approx.	
Brass	0.50 approx.	0.56 approx.	
Aluminum	0.48 approx.	0.53 approx.	

Others

- This product has been developed / produced for industrial use only.
- The output does not incorporate a short-circuit protection circuit.
 Do not connect it directly to a power supply or a capacitive load.
- Do not use during the initial transient time (50 ms) after the power supply is switched on.
- Extension up to total 100 m 328.084 ft is possible with a 0.3 mm², or more, cable.

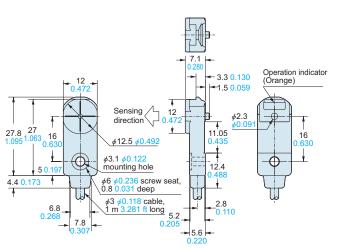
GX-H8□

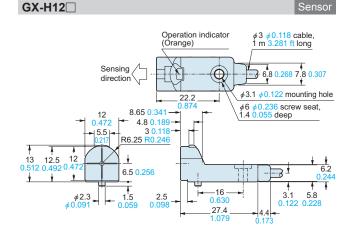
Sensor

Operation indicator (Orange) Sensing 8.55 direction 7.7 0.303 23 0.906 11.5 22.5 <u>♥</u> 6.5 φ3.1 <mark>φ</mark>0.12 9.75 mounting hole \$\phi 3 \phi 0.118 \text{ cable,} \\ 1 \text{ m 3.281 ft long} 2.65 0.03 **►** 6.3

Operation indicator (Orange) Sensing direction φ3 φ0.118 cable, 1 m 3.281 ft long 6.8 **←**2 0.079 3.7 0.146 → **-** R4.25 3.85 2.4 0.09 9 1 3-4.8 0.189 5.3 0.209

GX-F12 Sensor 8.6 0.3 4.6 0.181 2.5 -0.098 0.039





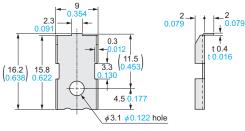
MS-GXL8-4

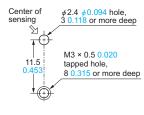
GX-F8□

Sensor mounting bracket for **GX-8 type** (optional)

Sensor

Mounting hole dimensions





Material: Stainless steel (SUS304)

1 pc. each of M3 (length 12 mm 0.472 in) truss head screw, nut, spring washer and plain washer is attached.

All information is subject to change without prior notice.



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