



DESCRIPTION

The HSN65LBC184DRG4 is a half-duplex RS-485 transceiver with $\pm 15\text{kV}$ IEC 61000-4-2 contact discharge protection. The HSN65LBC184DRG4 contains one driver and one receiver. The device features fail-safe circuitry, which guarantees a logic-high receiver output when the receiver inputs are open or shorted. This means that the receiver output will be logic high even if all transmitters on a terminated bus are disabled. The HSN65LBC184DRG4 features reduced slew-rate driver that minimizes EMI and reduces reflections caused by improperly terminated cables, allowing error-free data transmission up to 500kbps. The HSN65LBC184DRG4 has a 1/8-unit load receiver input impedance that allows up to 256 transceivers on the bus.

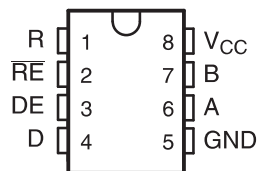
FEATURES

- TIA/EIA RS-485/RS-422 compliant ESD protection
- Integrated Transient Voltage Suppression
- Contact discharge $\pm 15\text{KV}$
- Data rates: 500 kbps
- Half-duplex Reduced slew rates for low EMI
- Common-mode input range: -7V to $+12\text{V}$

APPLICATIONS

- RS-485 Communications
- Level Translators
- Transceivers for EMI-Sensitive Applications
- Industrial Control Local Area Networks
- Energy Meter Networks
- Lighting Systems

PIN CONFIGURATION



SOP-8

Pin Functions

| PIN | | I/O | DESCRIPTION |
|------------------------|-----|---------------------|--|
| NAME | NO. | | |
| A | 6 | Bus input/output | Driver output or receiver input (complementary to B) |
| B | 7 | Bus input/output | Driver output or receiver input (complementary to A) |
| D | 4 | Digital input | Driver data input |
| DE | 3 | Digital input | Active-HIGH driver enable |
| GND | 5 | Reference potential | Local device ground |
| R | 1 | Digital output | Receiver data output |
| $\overline{\text{RE}}$ | 2 | Digital input | Active-LOW receiver enable |
| V _{CC} | 8 | Supply | 4.75-V to 5.25-V supply |



FEATUER DESCRIPTION

| Transmitting | | | | |
|--------------|----|----|----------|--------|
| Inputs | | | Outputs | |
| /RE | DE | DI | B | A |
| X | 1 | 1 | 0 | 1 |
| X | 1 | 0 | 1 | 0 |
| 0 | 0 | X | High-Z | High-Z |
| 1 | 0 | X | Shutdown | |

| Receiving | | | |
|-----------|----|---------------|----------|
| Inputs | | Outputs | |
| /RE | DE | A-B | RO |
| 0 | X | $\geq -0.05V$ | 1 |
| 0 | X | $\leq -0.2V$ | 0 |
| 0 | X | Open/shorted | 1 |
| 1 | 1 | X | High-Z |
| 1 | 0 | X | Shutdown |

ABSOLUTE MAXIMUM RATINGS

| Parameter | Symbol | Rating | Units |
|----------------------------|-----------------|------------------------------|-------|
| Power Supply | V _{CC} | +7 | V |
| Control Input Voltage | /RE, DE | -0.3 to V _{CC} +0.3 | V |
| Transmitter Input Voltage | DI | -0.3 to V _{CC} +0.3 | V |
| Transmitter Output Voltage | A, B | -8 to +13 | V |
| Receiver Input Voltage | A, B | -8 to +13 | V |
| Receiver Output Voltage | RO | -0.3 to V _{CC} +0.3 | V |
| Operating Temperature | -- | -25 to +85 | °C |



RECOMMENDED OPERATING CONDITIONS

($V_{CC}=+5V\pm 5\%$, $T_A=-40^{\circ}C\sim +85^{\circ}C$, Typical Values are $V_{CC}=+5V$ and $T_A=25^{\circ}C$) (Note 1)

| Parameter | Symbol | Conditions | MIN | TYP | MAX | UNITS | |
|---|-----------------|--|------------------|------|----------|------------|---------|
| Power Supply | V_{CC} | | 4.5 | | 5.5 | V | |
| Driver | | | | | | | |
| Differential Driver Output (no load) | V_{OD1} | Figure 1 | | | 5 | V | |
| Differential Driver Output | V_{OD2} | Figure 1, $R = 27\ \Omega$ | 1.5 | | | V | |
| Change in Magnitude of Differential Output Voltage (Note 2) | ΔV_{OD} | Figure 1, $R = 27\ \Omega$ | | | 0.2 | V | |
| Driver Common-mode Output Voltage | V_{OC} | Figure 1, $R = 27\ \Omega$ | | | 3 | V | |
| Change in Magnitude of Common-Mode | ΔV_{OC} | Figure 1, $R = 27\ \Omega$ | | | 0.2 | V | |
| Input High Voltage | V_{IH1} | DE, DI, /RE | 2.0 | | | V | |
| Input Low Voltage | V_{IL1} | DE, DI, /RE | | | 0.8 | V | |
| DI Input Hysteresis | V_{HYS} | | | 100 | | mV | |
| Input Current (A and B) | I_{IN4} | DE = GND, $V_{CC} =$ GND or 5.25V | $V_{IN} = 12\ V$ | | 125 | μA | |
| | | | $V_{IN} = -7\ V$ | | -75 | | |
| Driver Short-Circuit Output Current | I_{OSD} | $-7V \leq V_{OUT} \leq V_{CC}$ | -100 | | | mA | |
| | | $0V \leq V_{OUT} \leq 12V$ | | | 100 | | |
| Receiver | | | | | | | |
| Receiver Differential Threshold Voltage | V_{TH} | $-7V \leq V_{CM} \leq 12V$ | -200 | -125 | -50 | mV | |
| Receive Input Hysteresis | ΔV_{TH} | | | 40 | | mV | |
| Receiver Output High Voltage | V_{OH} | $I_O = -4\ mA, V_{ID} = -50\ mV$ | $V_{CC}-1.5$ | | | V | |
| Receiver Output Low Voltage | V_{OL} | $I_O = 4\ mA, V_{ID} = -200\ mV$ | | | 0.4 | V | |
| Three-State Output Current at Receiver | I_{OZR} | $0.4V \leq V_O \leq 2.4V$ | | | ± 1 | μA | |
| Receive Input Resistance | R_{IN} | $-7V \leq V_{CM} \leq 12V$ | 96 | | | k Ω | |
| Receiver Output Short-Circuit Current | I_{OSR} | $0V \leq V_{RO} \leq V_{CC}$ | ± 7 | | ± 95 | mA | |
| Supply Current | | | | | | | |
| Supply Current | I_{CC} | No load; /RE = DI = GND or V_{CC} | DE = V_{CC} | | 150 | 600 | μA |
| | | | DE = GND | | 185 | 600 | μA |
| Supply Current in Shutdown Mode | I_{SHDN} | DE = GND, /RE = V_{CC} , DI = V_{CC} or GND | | | 10 | μA | |

Note 1: All currents into the device are positive. All currents out of the device are negative. All voltages are referred to device ground unless otherwise noted.

Note 2: ΔV_{OD} and ΔV_{OC} are the changes in V_{OD} and V_{OC} , respectively, when the DI input changes state.



SWITCHING CHARACTERISTICS

($V_{CC}=+5V\pm 5\%$, $T_A=-40^{\circ}C\sim +85^{\circ}C$, Typical Values are $V_{CC}=+5V$ and $T_A=25^{\circ}C$)

| Parameter | Symbol | Conditions | MIN | TYP | MAX | UNITS |
|--|------------------|---|-----|-----|-----|-------|
| Driver Input to Output | T_{DPLH} | Figure 3 and 5, $R_{DIFF} = 54 \Omega$ $C_{L1} = C_{L2} = 100 \text{ pF}$ | | 450 | 800 | ns |
| | T_{DPHL} | | | 450 | 800 | |
| Driver Output Skew $ T_{DPLH} - T_{DPHL} $ | T_{DSKEW} | Figure 3 and 5, $R_{DIFF} = 54 \Omega$ $C_{L1} = C_{L2} = 100 \text{ pF}$ | | | 100 | ns |
| Driver Rise or Fall Time | T_{DR}, T_{DF} | Figure 3 and 5, $R_{DIFF} = 54 \Omega$ $C_{L1} = C_{L2} = 100 \text{ pF}$ | | 150 | 500 | ns |
| Maximum Data Rate | F_{MAX} | | 500 | | | kbps |
| Driver Enable to Output High | T_{DZH} | Figure 4 and 6, $C_L = 100 \text{ pF}$, S2 | | | 200 | ns |
| Driver Enable to Output Low | T_{DZL} | Figure 4 and 6, $C_L = 100 \text{ pF}$, S1 | | | 200 | ns |
| Driver Disable Time from Low | T_{DLZ} | Figure 4 and 6, $C_L = 15 \text{ pF}$, S1 | | | 300 | ns |
| Driver Disable Time from High | T_{DHZ} | Figure 4 and 6, $C_L = 15 \text{ pF}$, S2 | | | 300 | ns |
| Receiver Input to Output | T_{RPLH} | Figure 7 and 9, $ V_{ID} \geq 2.0V$, rise and fall time of $V_{ID} \leq 15\text{ns}$ | | 450 | 800 | ns |
| | T_{RPHL} | | | | | |
| $ T_{RPLH} - T_{RPHL} $ Differential Receiver Skew | T_{RSKD} | Figure 7 and 9, $ V_{ID} \geq 2.0V$, rise and fall time of $V_{ID} \leq 15\text{ns}$ | | 30 | | ns |
| Receiver Enable to Output Low | T_{RZL} | Figure 2 and 8, $C_L = 100 \text{ pF}$, S1 | | 20 | 50 | ns |
| Receiver Enable to Output High | T_{RZH} | Figure 2 and 8, $C_L = 100 \text{ pF}$, S2 Closed | | 20 | 50 | ns |
| Receiver Disable Time from Low | T_{RLZ} | Figure 2 and 8, $C_L = 100 \text{ pF}$, S1 Closed | | 80 | 150 | ns |
| Receiver Disable Time from High | T_{RHZ} | Figure 2 and 8, $C_L = 100 \text{ pF}$, S2 Closed | | 80 | 150 | ns |
| Time to Shutdown | T_{SHDN} | | | 50 | 300 | ns |
| Driver Enable from Shutdown to Output High | $T_{DZH(SHDN)}$ | Figure 4 and 6, $C_L = 15 \text{ pF}$, S2 Closed | | | 200 | ns |
| Driver Enable from Shutdown to Output Low | $T_{DZL(SHDN)}$ | Figure 4 and 6, $C_L = 15 \text{ pF}$, S1 Closed | | | 200 | ns |
| Receiver Enable from Shutdown to Output High | $T_{RZH(SHDN)}$ | Figure 2 and 8, $C_L = 100 \text{ pF}$, S2 Closed | | | 300 | ns |
| Receiver Enable from Shutdown to Output Low | $T_{RZL(SHDN)}$ | Figure 2 and 8, $C_L = 100 \text{ pF}$, S1 Closed | | | 300 | ns |



TEST CIRCUITS AND TIMING DIAGRAMS

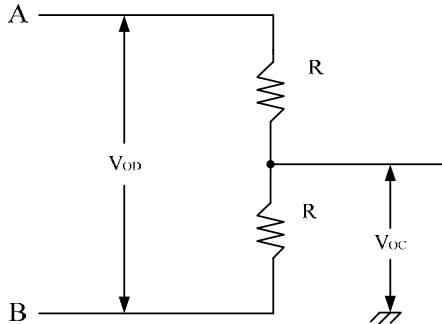


Figure 1: Driver DC Test Load

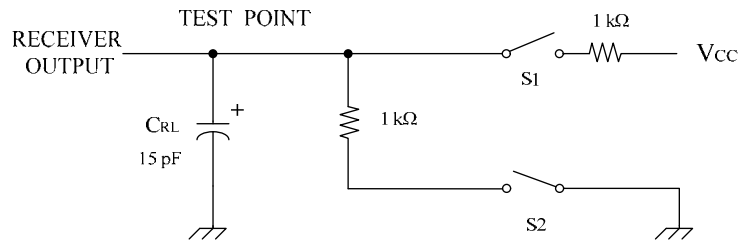


Figure 2: Receiver Enable/Disable Timing Test Load

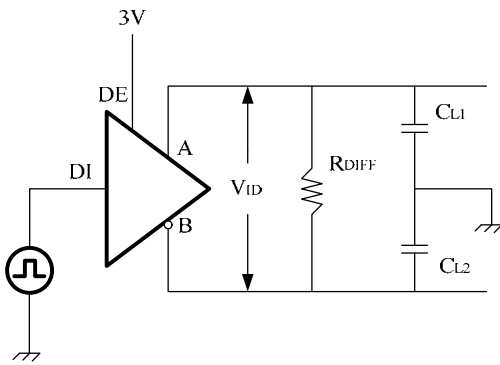


Figure 3: Driver Timing Test Circuit

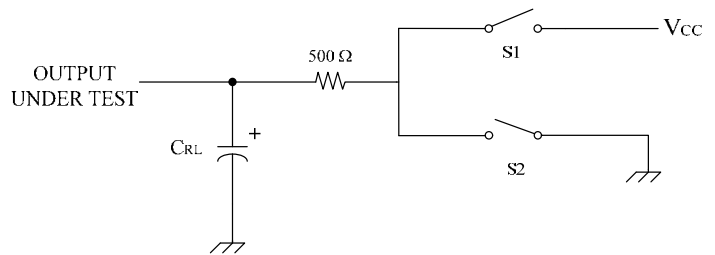


Figure 4: Driver Enable/Disable Timing test Load

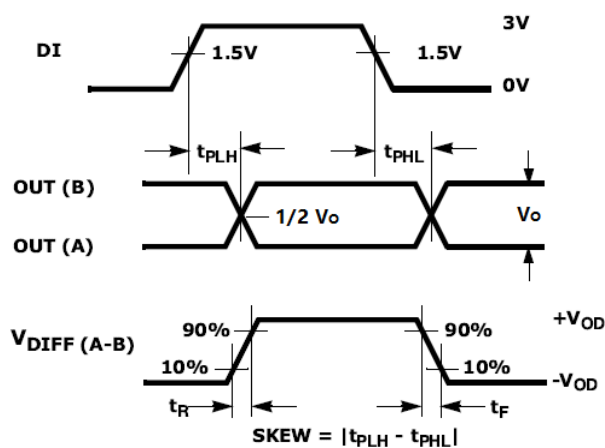


Figure 5: Driver Propagation Delays

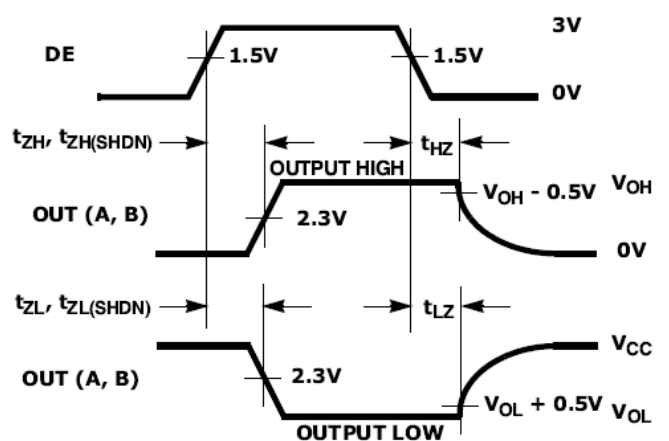


Figure 6: Driver Enable and Disable Times

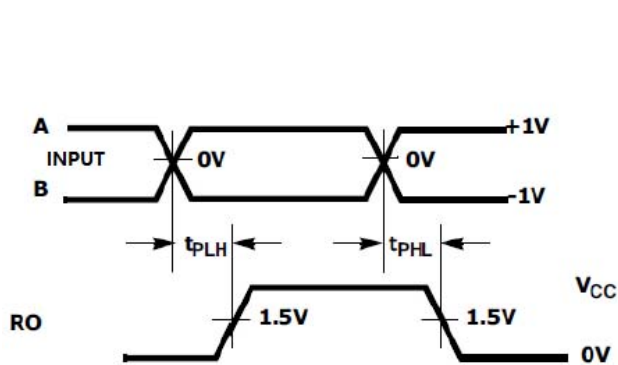


Figure 7: Receiver Propagation Delays

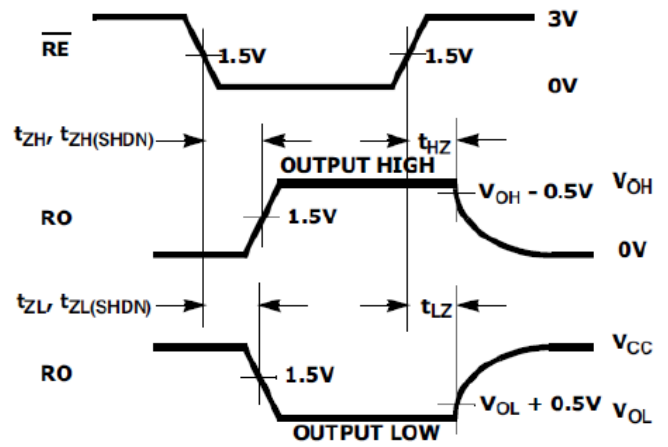


Figure 8: Receiver Enable and Disable Times

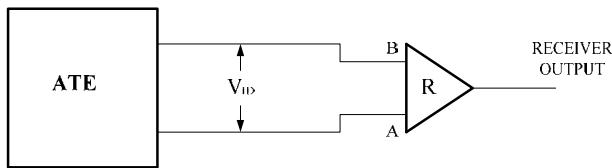
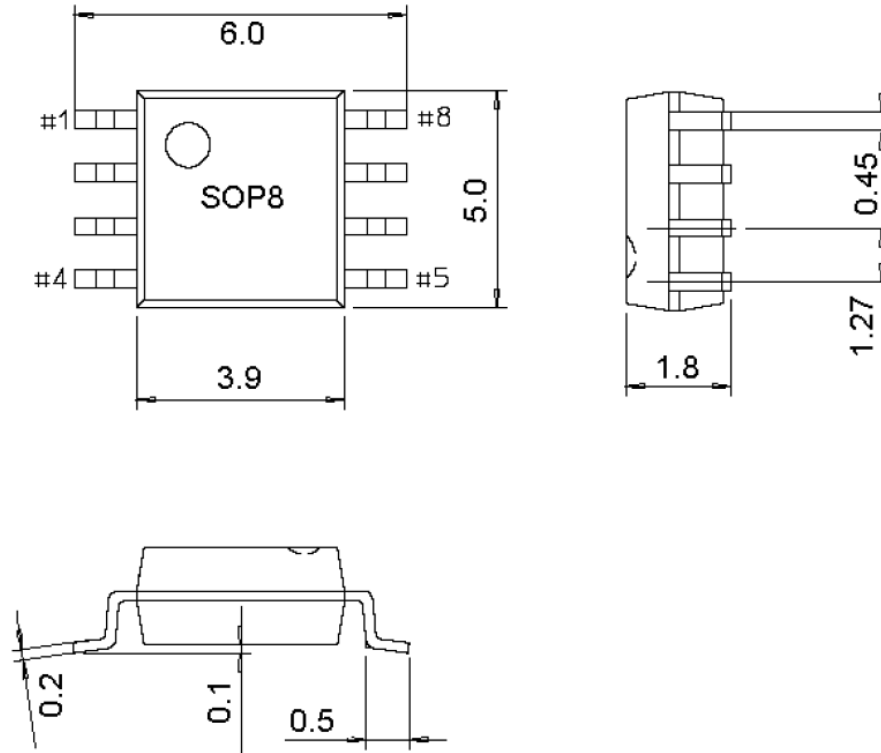


Figure 9: Receiver Propagation Delay Test Circuit



PACKAGE OUTLINE DIMENSIONS

SOP-8





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