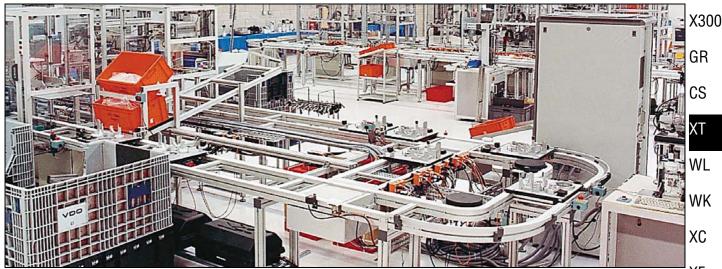
Modular pallet conveyor system XT

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Introduction



System description

The XT conveyor is a twin-track, flexible plastic chain pallet conveyor. The system is especially well suited for manual and automatic assembly and test systems in the automotive and electrical/electronics industries. The modular concept allows simplified engineering and ordering, as well as fast configuration together with plug and play capabilities for improved productivity.

Examples of application areas

Manual and automatic assembly and test systems in the automotive and electrical/electronics industries. Examples: gearboxes, computers, sewing machines, mobile phones, automotive seat guiderails, eyeglasses, injection-moulded parts, fishing reels, car instrument kits

Module concept

The standard modules can be split into six groups - conveyors, transfers, stops, locates, lift-and-rotates and supports. Each module is quickly adaptable and reusable for ELV future demands and can easily be integrated with Flex-Link's large range of single strand pallet conveyor systems.

Pallets

FlexLink's standard chains and integrated guide rails systems allow for accumulation through the entire system, including bends, as well as easy and straightforward integration of stops, locate stations as well as transfer units with a minimum of controls.

CC X45

PO

XS X65

X85

X85P

X65P

XH

XKP

XK

X180

GR

WL WK

XC

XF

CTL **FST**

TR

APX

System data

- · 25 m maximum conveyor length
- 20 m/min maximum conveyor speed
- Standard pallet sizes from 240×240 mm up to 640×640 mm, including rectangular sizes
- 30 kg maximum pallet weight (8 kg pallet weight/100 mm conveyor
- 250 kg maximum accumulated weight at 5 m/min.
- Maximum permitted load per link 0,5 Kg (XT-Compact)
- Maximum permitted load per link 1,0 Kg

Typical noise levels

During normal conditions a noise level below 65 dB(A) can be obtained in an XT conveyor system, including transfers, stops, etc. However, be aware that the pneumatic components (valves, etc.) very much affect the noise level if they are not enclosed correctly. Also, throttle valves must be adjusted correctly at transfers, stops, etc. The following table shows typical noise levels.

Speed m/min.	5	10	15	20	30*
dB(A)	56	58	61	65	70

^{*}No standard speed

The modular concept

Introduction

The modular concept includes six groups of modules that have been defined to suit the various industrial demands.

Most of the conveyor modules can be connected back to back by a connecting kit to form the desired conveyor layout. Other modules such as the transfer module or the locating function module can be incorporated as required.

The module groups are:

- Conveyor modules
- Support modules
- · Transfer modules
- · Stop function module
- · Locating function modules
- Lift-and-rotate modules

Each module is explained in more detail later on in this section of the catalogue.

Accessories and spare parts

Accessories and spare parts for the XT modules can also be ordered. Those products are listed after the module descriptions. See page 353 to 379.

Ordering process

Every XT module has its own unique order code which can be found in each module description. The various options available for each module are shown in the order code and all the parameters have to be specified when ordering.

It is important to know that by ordering for example a conveyor module, you do not automatically get a support module. This has to be ordered separately.

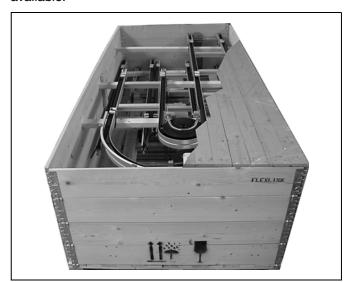
Product configurator

The easiest way to order XT modules is by using the online product configurator.

You can find this webbased configurator at the Flex-Link website http://www.flexlink.com.

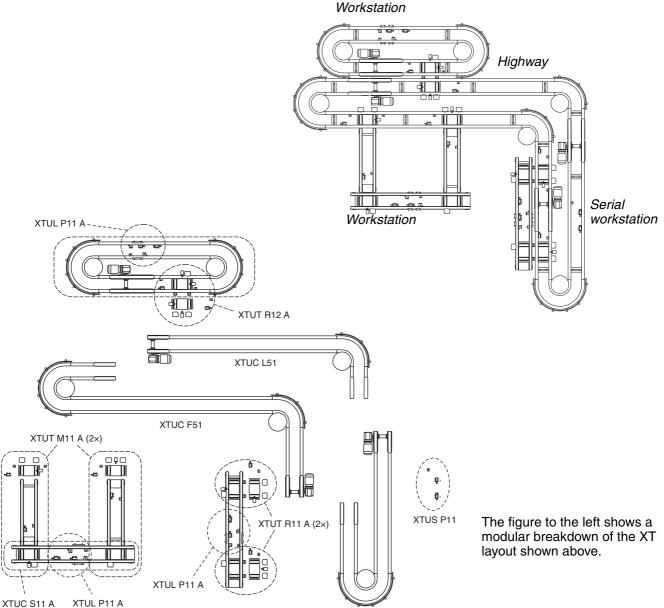
Shipment

Modules are normally delivered in flat boxes with a maximum length of approximately 3 m. See photo below. Conveyor modules will be delivered in sections of maximum 3 m which are easy to reassemble. More detailed information regarding each module is provided in the section describing the modules. An assembly manual is available describing how to assemble and connect the modules. Maintenance and spare parts manuals are also available.



Typical XT conveyor layout

The figure below shows a typical conveyor layout, built by connecting various XT modules. Note that support modules are not shown in this overview. For each conveyorand transfer module, a support module has to be ordered separately, see page 343, "XT support modules".



Pallet flow in a highway

Characteristic for a highway is a continuous circulation of pallets, waiting for calling from a transfer operation into a parallel flow, for instance a workstation. In order to minimize the noise level and not disturbing the pallet more than necessary in a highway, the FlexLink philosophy is that by default most stop functions attached to a highway are not activated. The stop function will only be activated if a pallet has to be transferred out from or into the highway.

Exception

XTUC J51

A Stop function module or a Locating function module attached directly to a highway will be seen as a serial workstation and the stop function of these are therefore always activated by default, i.e. all single pallets will be stopped. This philosophy applies to all XT standard modules.

X45

CC

XS

X65 X65P

X85

X85P

XH

XK XKP

Alti

X180 X300

GR

CS

ΧT

WL

WK

XC

XF

XD

ELV

CTL

OIL

FST

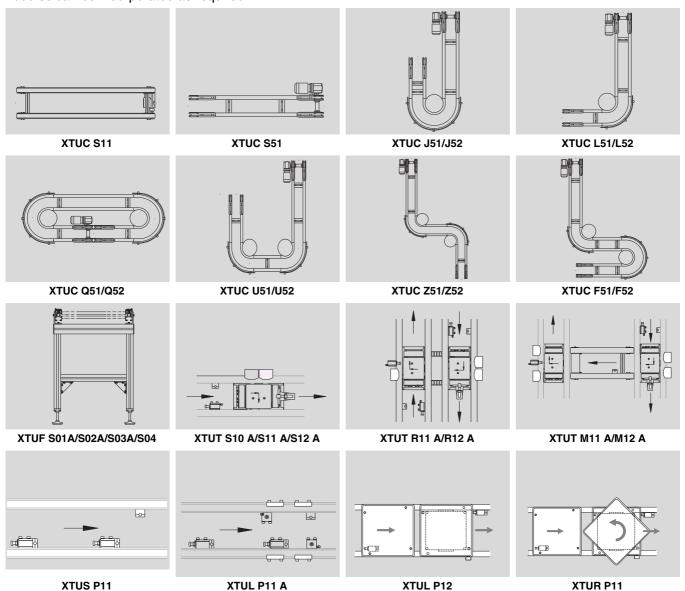
TR

APX

Available XT modules

Below is an overview of the various modules presented. The conveyor modules can be connected back to back to form the desired conveyor layout. Transfer and locating modules can be incorporated as required.

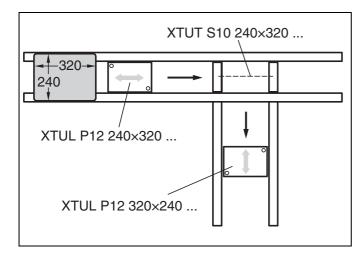
For more information about the modules, please see the detailed information under each module section later on in this document.



Definition of parameters

Pallet width (PW) × pallet length (PL)

Pallet width and pallet length. PL is basically the pallet dimension in the direction of pallet movement in the main flow. In some modules the pallet moves "sideways", for example when transferred from one line to another. See the module descriptions for PL/PW definitions in each specific case. The figure below shows an example.



Length (L1, L2 and L3)

The length of each conveyor section as defined by each module drawing.

Length (A)

Length A is the distance between the two inner beams (outer edges).

Height (H1)

H1 is equivalent to the chain height.

Height (H2)

H2 is equivalent to the chain height of a second, lower, conveyor, if applicable.

Standard/Conductive (AS)

- Standard version (AS0)
- Conductive version (AS2). See "Static electricity" on page 339.
- Dissipative version (AS3). Only for XT Compact.

Slide rail configuration

The following figures show the four different slide rail options applicable to XT conveyors.

P0

CC

X45

XS

X65

X65P

X85

X85P

XH

XK

XKP

CS

XF

XD

ELV

CTL

FST

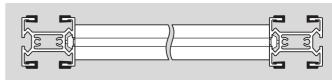
TR

APX

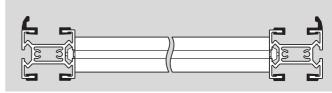
IDX

335

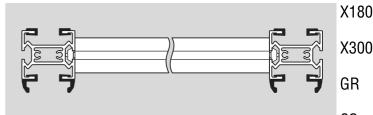
G0: No pallet side guides



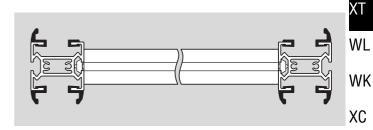
G2: Pallet side guides



G4: No pallet side guides, protection of return chain



G6: Pallet side guides, protection of return chain



Motor speed (V)

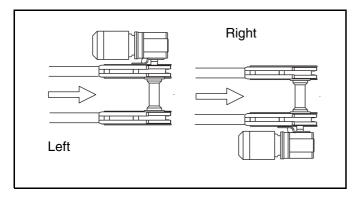
Equivalent to conveyor chain speed in m/min.

Motor type (MT)

The motor unit can be mounted on the:

- Left side of the conveyor
- Right side of the conveyor
- · Below the conveyor (mid-mounted)

Left/Right refers to the location of the motor in relation to the direction of chain travel. See figure.



European /American motor (Hz)

Operating frequency of the motor:

- European, 50 Hz
- American, 60 Hz.

Queue stop (Q)

Queue stop is used for queue accumulation

- Queue stop Q01
- No queue stop Q00

Pallet damping (D)

This parameter determines if a non-shock absorbing or shock absorbing stopper is needed.

- No damping of pallet, max gueue 200 kg (D00)
- Max damping of pallet, max queue 35 kg (D01)
- Max damping of pallet, max queue 100 kg (D02).

Function (F)

 Use of F depends on module. Currently used with support modules XTUF and modules XTUL P11 A and XTUL P12.

Electric control (E)

Options: E00-E02

- Without sensors
- With PNP sensors
- With NPN sensors

Currently used with modules XTUL P12 and XTUR P11. See module descriptions for details.

General information

Support modules

Note that the conveyors and transfers are not delivered with support modules. They must be ordered separately (see page 343).

Standard or conductive

The conveyors and transfers can be delivered in standard and conductive versions, see "Ordering information". See also "Static electricity" on page 339.

Note on energy consumption

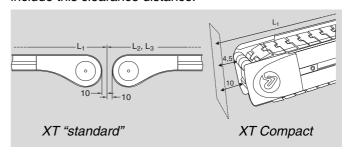
Since friction build-up is maximum in the bends, keep conveyor sections which are separated from the drive unit by bends as short as possible, to minimize energy consumption.

Components and accessories

For detailed component information, see page 353–378.

Minimum clearance distance

When two conveyors meet end to end, they must be separated by a minimum clearance distance. See the figure. The dimensions shown in the product drawings (L1/L"/...) include this clearance distance.



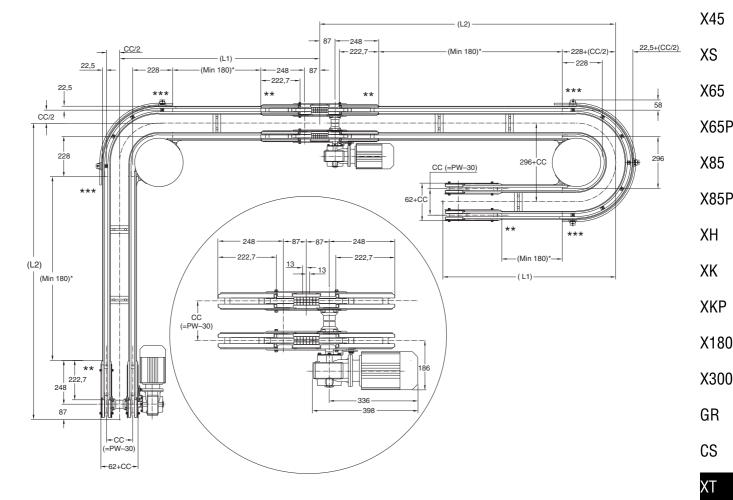
Maximum load on conveyors

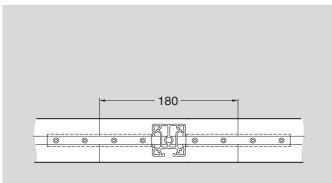
See "Chain tension calculations" software, and "Technical information" on page 338.

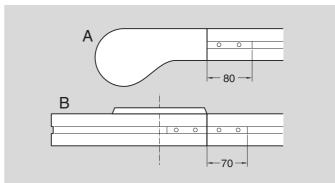
More information

For logic flowchart and pneumatic diagram: see separate document *XT logic flowcharts*.

General dimensions







Note

Attachment of a support module normally requires more space in this section than 180 mm.

Near a drive unit** or idler end unit** (Fig. A), or a wheel bend*** (Fig. B), the T-slots are occupied by connecting strips.

CTL

WL

WK

XC

XF

XD

ELV

UIL

FST

TR

APX

^{*} Minimum length of conveyor beam section.

Technical information

Chain tension calculations

Chain tension limit, XT conveyor

See diagrams 1 and 2. See also chain tension calculation software.

(AS0 = standard chain; AS1 = ISD chain; AS2 = conductive chain)

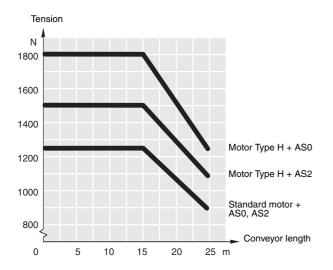


Diagram 1. Maximum chain tension vs. conveyor length

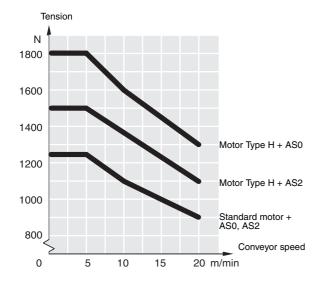


Diagram 2. Maximum chain tension vs. conveyor speed

Chain tension limit, XT Compact conveyor

Use chain calculation software.

50 Hz motor

Speed (m/min)	V05	V10	V15	V20	
Fmax (N)	360	350	220	190	

60 Hz motor

Speed (m/min)	V06	V12	V18
Fmax (N)	360	280	170

Chain tension limit per track

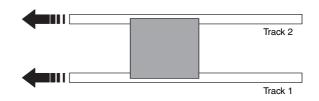
XT convevor

Chain type	AS0	AS1	AS2
Fmax (N)	900	450	750

XT Compact conveyor

Chain type	AS0	AS1	AS2
Fmax (N)	180	180	180

(AS0 = standard chain; AS1 = ISD chain; AS2 = conductive chain)



Technical data

Drive units

Drive unit	Maximum traction force, N
End drive unit	1250
End drive unit, Type H	1800
Catenary drive unit	1250

Chains, general specifications

Parameter	XT	XT Compact
Weight (plain chain) kg/m	0,62	0,28
Tensile strength at 20 °C	900 450 (ISD) 750 (conductive)	180 180 (ISD) 180 (conductive)
Hardness H _{RB}	120	120
Water absorption after 24 h at 20 °C	0,2 %	0,2 %

Chain strength and expansion vs. temperature

Temperature °C	-20	0	20	40	60	80	100	120
Tensile strength factor								
Linear expansion %	-0,4	-0,2	0	0,2	0,5	0,8	1,0	1,3

Friction between chain and slide rail

XTCR 25 U/ XTCR 3 UB (UHMW-PE, white)...... 0,15–0,3

The coefficient of friction is normally the lower value at the startup of a new conveyor. It will increase as the contact surfaces wear in. Lubrication will reduce the coefficient of friction.

Technical information (continued)

_ P0

Friction between chain and pallet

CC

In most cases, the coefficient of friction for contact between plain chain and pallet is between 0,1 and 0,35.

X45

Temperature limits

XS

A conveyor can operate continuously at environment temperatures from $-20\,^{\circ}\text{C}$ to $+60\,^{\circ}\text{C}$. Temperatures up to $+100\,^{\circ}\text{C}$ can be tolerated for short periods (cleaning, rinsing).

X65

Maximum conveyor length

X65P

The maximum length of a conveyor depends on the tension in the chain, the speed, and the capacity of the drive unit.

X85 X85P

It is important to calculate and compare the maximum chain tension and the capacity of the drive unit in the following situations:

ХН

Heavy load

XK

Accumulation

XKP

High speedLong conveyor

X180

• Frequent starts and stops (high service factor).

X300

Static electricity

GR

The standard plastic materials used for conveyors all have low electrical conductivity. This means that static electricity can build up on the conveyor. If the chain runs on plastic slide rails, no inherent discharge path exists for the static electricity.

CS

When a conveyor is running under normal operating conditions but without pallets, the following static build-up can be measured:

ΛI

 At the drive unit
 2000–2500 V

 At the idler end unit
 400–500 V

 At a wheel bend
 400–500 V

 At a straight section
 300–400 V

WL WK

A pallet running on the conveyor can also build up static electricity. The worst case is with accumulated pallets. Discharge is normally taking place when the pallets are transferred to or from the conveyor. In static sensitive applications, a number of measures can be taken to reduce the risk of excessive static charges.

XC

1 Ensure that the relative humidity is minimum 40%.

XF XD

2 Install static discharge wipers immediately before sensitive points on the conveyor. ELV

Components for static sensitive environments

CTL

Some of FlexLink's chains and slide rails can be ordered in carbon loaded versions. The carbon loaded material has high conductivity.

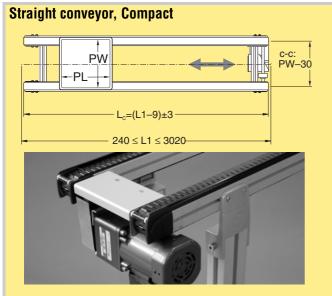
FST

Contact your FlexLink Systems representative for additional information.

TR

APX IDX

Conveyor module S11 Compact



Straight conveyor module, Compact XTUC S11 ...

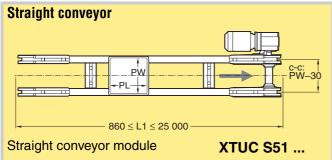
XT Compact products use standard 1-phase motors, 240 V 50 Hz or 115 V 60 Hz. For use as stand-alone unit, as perpendicular link between two XT conveyor modules, or in-line with another conveyor module. Reversible operation is possible. The module is delivered fully assembled.

Configuration: see page 342.

The Compact series modules use a different type of conveyor beam and chain as compared to other modules. Type XTUC S11 ... is the only stand-alone Compact conveyor module, but Compact conveyors are used in Transfer modules.

XT conveyor modules

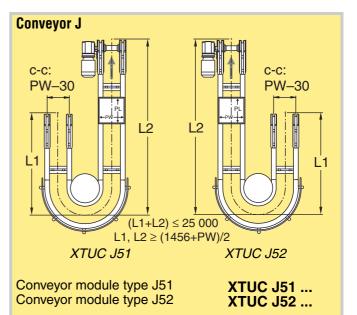
Conveyor module S51



For use as a stand alone unit, in-line with or perpendicular to another module. Reversible operation is <u>not</u> possible.

Configuration: see page 342.

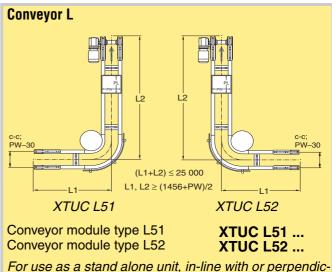
Conveyor module J51/J52



For use as a stand alone unit, in-line with or perpendicular to another module. Reversible operation is <u>not</u> possible.

Configuration: see page 342.

Conveyor module L51/L52



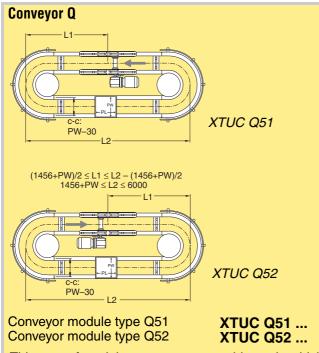
For use as a stand alone unit, in-line with or perpendicular to another module. Reversible operation is <u>not</u> possible.

Configuration: see page 342.

X300

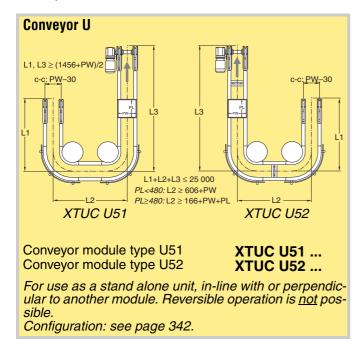
GR

Conveyor module Q51/Q52

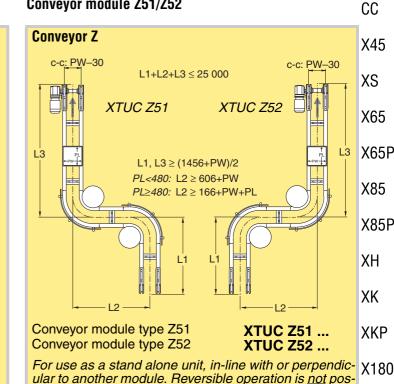


This type of module uses a catenary drive unit, which means that the chain runs on the top side only. For use as a stand alone unit or as a transfer module to another module. Reversible operation is not possible. Configuration: see page 342.

Conveyor module U51/U52

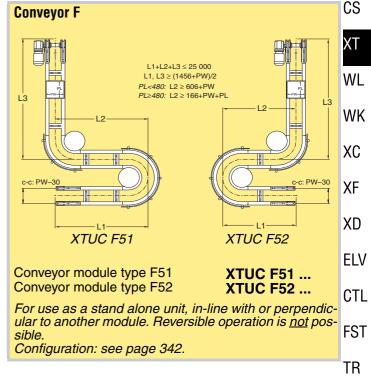


Conveyor module Z51/Z52



Conveyor module F51/F52

Configuration: see page 342.



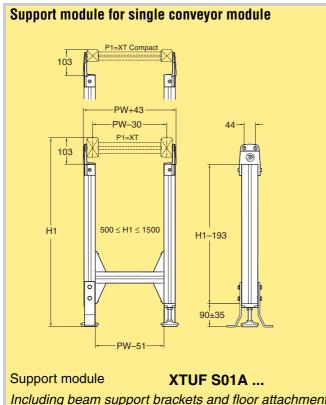
APX

Conveyor module configuration examples

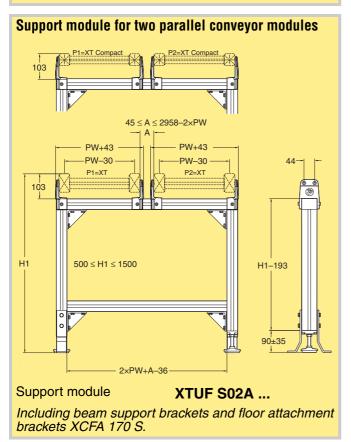
Parameter	Pallet width × Pallet length (mm)	Lengths (mm)	Cor	anda nduc ssipa	tive/	Slid		il co tion	nfig-	Motor speed (m/min)					N	/loto	r typ	50 Hz/6 Hz moto								
	PW×PL	L1-L2-L3		AS			(G							٧							N	ſΤ	Hz		
Options	240×240 240×320 320×240 320×240 320×400 400×320 400×400 400×640 480×400 480×480 640×480 640×640	Dimension ranges: see module drawings	AS0 Standard version	AS2 Conductive version	AS3 Dissipative version	09	G2	G4	99	*		* V20) with		drive				orqu	e arr		L Left-mounted	Right-mounted	M Mid-mounted	HM Heavy mid-mounted	E1 European (50 Hz)	A1 American (60 Hz)
XTUC S11	PW	L1		AS			(G	•						٧		•					N	İΤ			Hz
XTUC S11	240	1834	AS 0				G2					V1 0											М		E1	
XTUC S51	PW	L1		AS			(G							٧							N	İΤ			Hz
XTUC S51	240	12350		AS 2		G0									V0 6						L					A1
XTUC J51/J52 XTUC L51/L52	PW×PL	L1- L2		AS			(G							V							N	İΤ			Hz
XTUC J51	240×240	2350-4750		AS 2				G4								V1 0								H M		A1
XTUC Q51/Q52	PW×PL	L1-L2		AS				G							V							N	ÍΤ			Hz
XTUC Q52		900-3000	AS 0				G2	-	-			V1 0									L				E1	
XTUC U51/U52 XTUC Z51/Z52 XTUC F51/F52	PW×PL	L1-L2-L3		AS				Ġ							V							N	ИT			Hz
XTUC U51	240×320	1200-1350- 1550	AS 0				G2			V0 0														H M	E1	

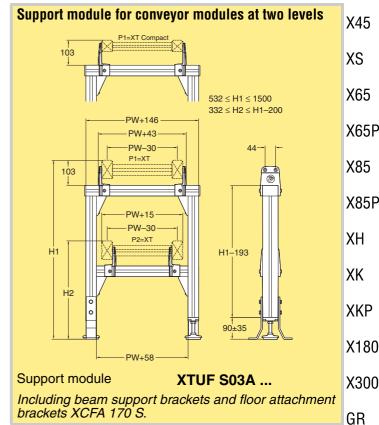
Parameters: see page 335.

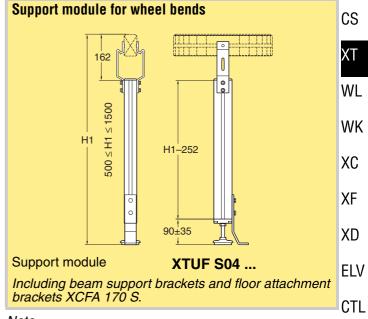
Support modules S01A/S02A/S03A/S04



Including beam support brackets and floor attachment brackets XCFA 170 S.







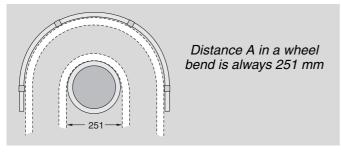
Note.

Two types of beam support brackets are used in the mod-FST ules: type 5052899 for standard XT, and type 5052621 for XT Compact. The brackets are also available sepa-TR rately. See page 365.

APX

Distance A

If two parallel conveyor modules are joined by a wheel bend, the distance between conveyors is fixed. In this case "distance A" in the designation code is always 251 mm. See figure.

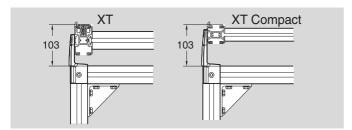


Delivery

The modules will be delivered fully assembled including beam support brackets and feet, and the screws and nuts required for connecting to an XT or XT Compact conveyor. Fasteners for connecting the support modules to the floor are not included. See also page 332, "The modular concept/Shipment".

Application usage

Recommended distance between two support modules is maximum 2 m.



Ordering information

See configuration examples below. The parameter F is used to ensure that the support module is delivered with the correct beam support brackets. It indicates the type of XT conveyor supported by the module (XT or XT Compact, or a combination of both).

Bracket type (F)
 (Definitions of P1 and P2: see figures on page 343.)

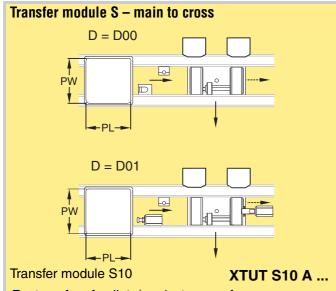
	_		
Type XTUF	F	P1	P2
S01A	01	XT	_
	02	XT Compact	_
S02A	01	XT	XT
	02	XT Compact	XT Compact
	03	XT	XT Compact
S03A	01	XT	XT
	02	XT Compact	XT Compact
	03	XT	XT Compact
	04	XT Compact	XT

Support module configuration examples

Parameter	Pallet width (mm)	Distance Height 1 Height 2 (mm) (mm) (mm)		E	Brack	et typ	е	
	PW	Α	H1	H2			F	
Options	240 320 400	Dimension ra	Dimension ranges: see module drawings.					r see e
	480 640				F01	F02	F03	F04
XTUF S01 A	PW		H1			ı	F	
XTUF S01 A	240		1225		01			
XTUF S02 A	PW	Α	H1				F	
XTUF S02 A	240	95	1375			02		
XTUF S03 A	PW		H1	H2			F	
XTUF S03 A	240		850	550		02		
XTUF S04			H1					
XTUF S04			1250					

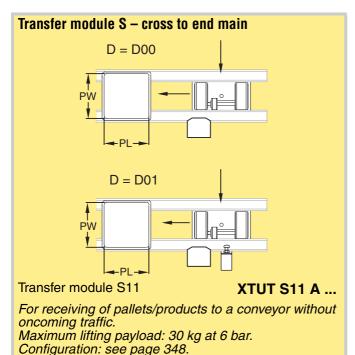
Parameters: see page 335.

Transfer module S10 A

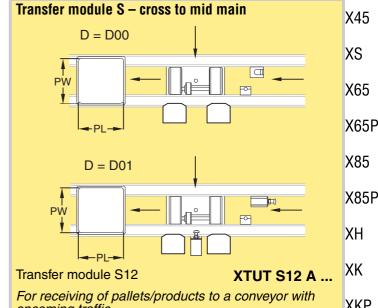


For transfer of pallets/products away from a conveyor. Maximum lifting payload: 30 kg at 6 bar. Configuration: see page 348.

Transfer module S11 A



Transfer module \$12 A



oncoming traffic.

Maximum lifting payload: 30 kg at 6 bar. Configuration: see page 348.

Motor

The transfer units are delivered with 15 m/min (E1) or 18 m/min (A1) motor.

Included in the delivery:

- One pneumatic transfer unit including the necessary proximity sensors.
- The necessary mounting hardware required for attachment to an XT or XT Compact conveyor.
- The required number of stoppers, dampers and sensor brackets based on the options selected.

XS

X65

X85

X85P

XKP

X180

GR

X300

CS

XΤ WL

WK

XC XF

XD

ELV

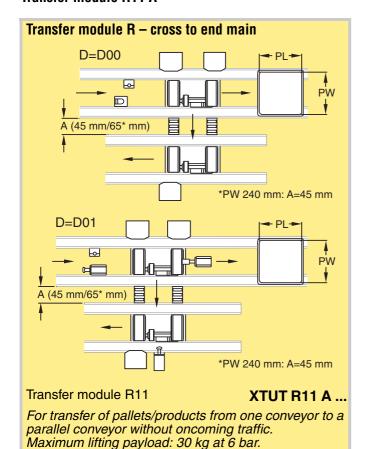
CTL

FST

TR

APX

Transfer module R11 A



Motor

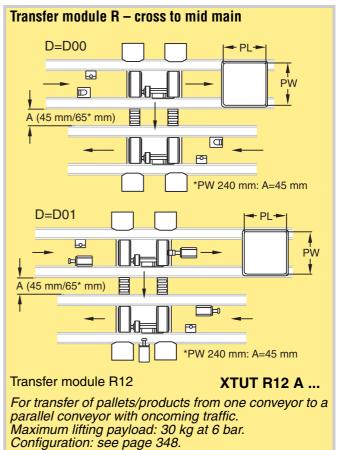
The transfer units are delivered with 15 m/min (E1) or 18 m/min (A1) motor.

Included in the delivery:

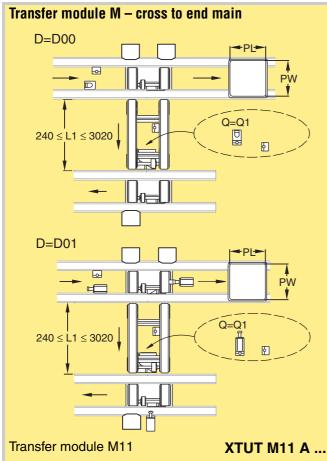
Configuration: see page 348.

- Two pneumatic transfer units including the necessary proximity sensors.
- The necessary mounting hardware required for attachment to an XT or XT Compact conveyor.
- 2 roller kits, distance A.
- The required number of stoppers, dampers and sensor brackets based on the options selected.

Transfer module R12 A



Transfer module M11 A



For transfer of pallets/products from the main conveyor to a parallel conveyor via an XT Compact conveyor, without oncoming traffic.

Maximum lifting payload: 30 kg at 6 bar. If L1 ≤ 210 + PW it is not possible to use queue stop in the traverse conveyor, i.e. only Q=Q00 is possible Configuration: see page 348.

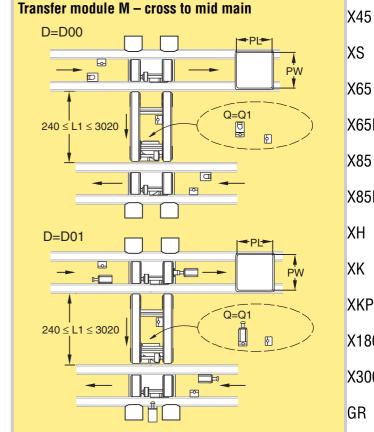
Motor

The transfer units are delivered with 15 m/min (E1) or 18 m/min (A1) motor

Included in the delivery:

- Two pneumatic transfer units including the necessary proximity sensors.
- One XT Compact conveyor, length L1, with mounting brackets.
- The necessary mounting hardware required for attachment to an XT or XT Compact conveyor.
- The required number of stoppers, dampers and sensor brackets based on the options selected.

Transfer module M12 A



For transfer of pallets/products from one conveyor to a parallel conveyor, via an XT Compact conveyor, with oncoming traffic.

Transfer module M12

Maximum lifting payload: 30 kg at 6 bar. If L1 ≤ 210 + PW it is not possible to use queue stop in the traverse conveyor, i.e. only Q=Q00 is possible Configuration: see page 348.

X65

X65P

X85P

XΗ

XKP

X180

X300

GR CS

XTUT M12 A ...

XΤ

WL WK

XC

XF

XD

ELV

CTL

FST

TR

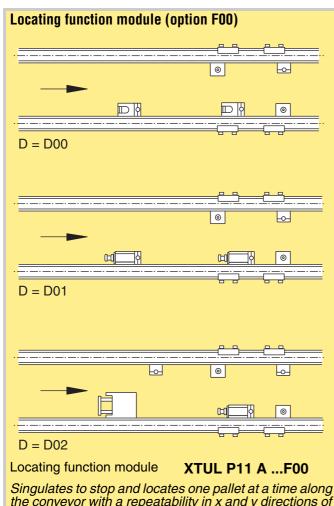
APX

Transfer module configuration examples

Parameter	Pallet width × Pallet length (mm)	Lengths (mm)	Distance (mm)	Condi Dissip				Motor	speed ((m/min)				European/American motor		Queue stop traverse conveyor		Pallet damping	
	PW×PL	L1	Α	Α	S				V				МТ	H	łz	(Q		0
Options	240×240 240×320 320×240 320×320 400×320 400×400 400×480 400×640 480×480 480×640 640×480 640×640	Dimensi ranges: s module di ings	see raw-			V05		Hz Hz	VZ0	90 /	60 Hz		Σ	E1 European (50 Hz)	A1 American (60 Hz)	Q00 No queue stop	Q01 Queue stop		D01 Damping, max queue 35 kg
XTUT S10 A XTUT S11 A XTUT S12 A	PW×PL			Α	S				V				МТ	ŀ	łz			[D
XTUT S11 A	240×320			AS0				V15					М	E1				D00	
XTUT R11 A XTUT R12 A	PW×PL		Α	Α	S				V				MT	ŀ	lz			[D
XTUT R11 A	240×320		45	AS0								V18	М		A1				D01
XTUT M11 A XTUT M12 A	PW×PL	L1	Α		S				V				MT		lz		Q	[D
XTUT M11 A	240×320	1350	45	AS0			V10*						М	E1		Q00			D01

Parameters: see page 335.

Locating function module P11 A F00



the conveyor with a repeatability in x and y directions of

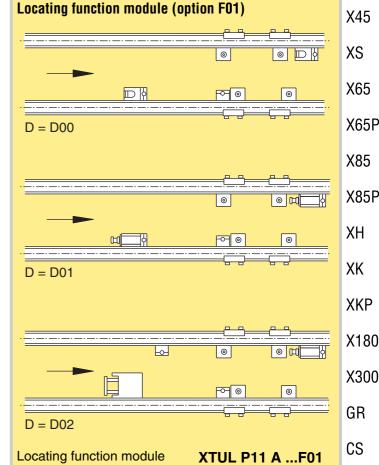
Two diagonal lift units with guide pins. Only for PW or PL ≤ 400 mm

Configuration: see page 352.

Included in the delivery:

- One locating station, including non-return throttle valves.
- The necessary number of stoppers and sensor brackets, based on the option selected.
- The necessary mounting hardware required for attachment to an XT or XT Compact conveyor.

Locating function module P11 A F01



Singulates to stop and locates one pallet at a time along the conveyor with a repeatability in x and y directions of ±0,05 mm.

Four lift units: two diagonal lift units with guide pins and two without guide pins.

Configuration: see page 352.

WK

XΤ

WL

XC

XF

XD

ELV

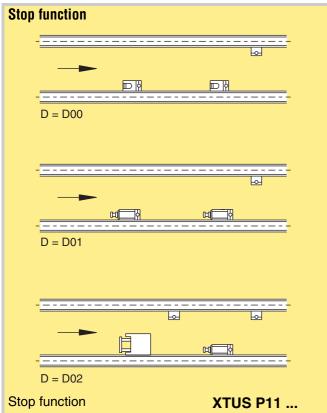
CTL

FST

TR

APX

Stop function module P11



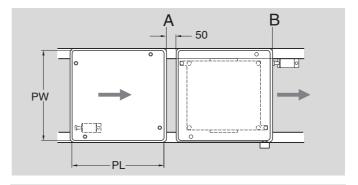
Singulates and stops one pallet at a time along the conveyor line with a repeatability of ± 1 mm. The stop units can be mounted on the opposite side of the beam to facilitate pallet stopping at the front end of the pallet. Configuration: see page 352.

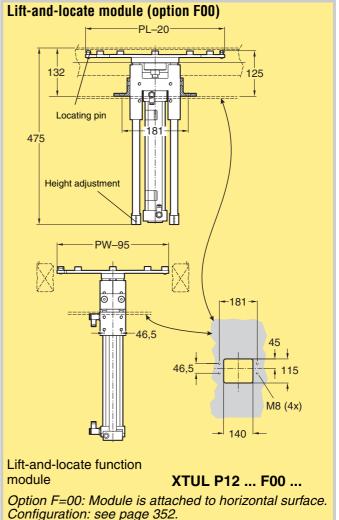
Included in the delivery:

- The necessary number of stoppers and sensor brackets, based on the option selected.
- The necessary mounting hardware required for attachment to an XT or XT Compact conveyor.

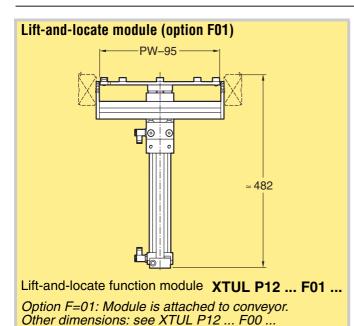
Lift-and-locate function module XTUL P12

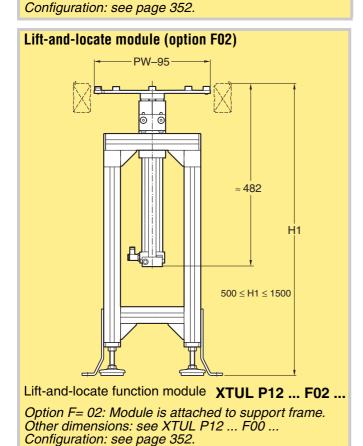
The lift-and-locate function is used when a product needs to be located at a specific height prior to a machine operation. The device can be mounted in three ways (options F00–F02).





Flex Link®



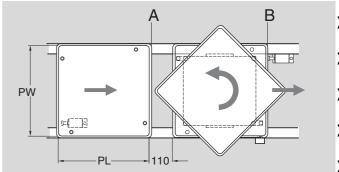


Delivery

- One lift-and-locate module, including non-return throttle valves.
- The necessary number of stoppers and sensor brackets, based on the option selected.
- The necessary mounting hardware required for attachment to an XT or XT Compact conveyor, depending on the F01 or F02 option.

Lift-and-rotate function module XTUR P11

The lift-and-rotate module can turn the pallet 180°. It can be useful in systems with a mix of bends and transfers, or in a process where the pallet needs to be rotated prior to a machine operation.



Note

To protect persons from the clamp risk, the unit must be covered.

Delivery

- One lift-and-rotate station, including non-return throttle valves
- The necessary number of stoppers and sensor brack- WL ets, based on the options selected
- The necessary mounting hardware required for connection to an XT or XT Compact conveyor.

X65

XS

X65P

X85

X85P

XΗ

XK XKP

X180

X300

GR

CS

XΤ

XC

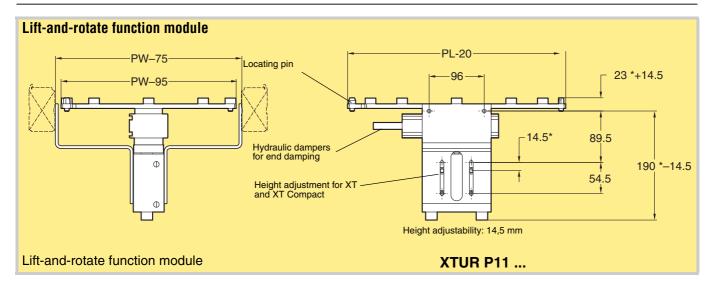
XF XD

ELV

CTL

FST TR

APX

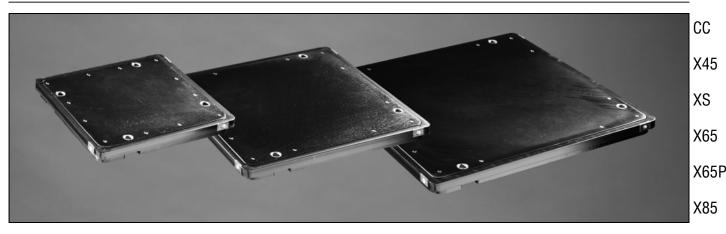


Function module configuration examples

Parameter	Pallet width × Pallet length (mm)	Height 1 (mm)	Pallet damping		Function			Electric control				
	PW×PL	H1		D			F			E		
Options	240×240 240×320 320×240 320×320 320×400 400×320 400×400 *400×640 *480×400 *480×400 *480×480 *640×480 *640×640 *Not for XTUR P11	500 mm< H1 <1500 mm If F=F00/F01: H1=0000	D00 No damping	D01 Damping, max queue 35 kg	D02 Damping, max queue 100 kg	Desc mod	riptior ule dra	r: see	E00 No sensors	E01 Two PNP sensors in cylinder unit	E02 Two NPN sensors in cylinder unit	
XTUS P11				D								
XTUS P11					D02							
XTUL P11 A				D			F					
XTUL P11 A			D00				F01					
XTUL P12	PW×PL	H1		D			F			Е		
XTUL P12	240×320	0000	D00				F01				E02	
XTUR P11	PW×PL			D	•		•	•		Е	•	
XTUR P11	400×400		D00								E02	

Parameters: see page 335.

Pallets P0



Introduction

Ten pallet sizes are available:

240 × 240 mm

240 × 320 mm

320 × 320 mm

 $320 \times 400 \text{ mm}$

 $400 \times 400 \text{ mm}$

 $400 \times 480 \text{ mm}$

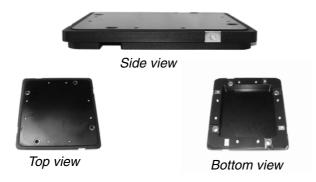
400 × 640 mm

480 × 480 mm

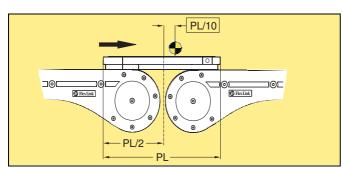
 $480 \times 640 \text{ mm}$

 $640 \times 640 \text{ mm}$

For non-standard pallet dimensions, or for other pallet plate materials than steel, frame section kits and bushing kits can be ordered. See next page.



Note!



In order to get a good transition between two conveyors or in a transfer station, max. displacement of point of gravity should not exceed ±PL/10.

Technical specifications

- Maximum load on the pallet is 80 N per 100 mm of pallet length (PL).
- Friction between pallet and chain, μ_p = 0,3 (under nor- $\chi_{\mbox{\scriptsize K}}$ mal conditions).
- The table below shows maximum pallet load for each χ_{KP} pallet size.

Size (PW × PL)	Pallet weight (kg)	Max load on pallet (kg)	X180
240 × 240 mm	2,6	17	<u> </u>
240 × 320 mm	3,5	22	X300
320 × 240 mm	3,5	16	1
320 × 320 mm	4,4	22	GR
320 × 400 mm	5,5	24	411
400 × 320 mm	5,5	20	cs
400 × 400 mm	6,8	23	US
400 × 480 mm	8,2	22	\
400 × 640 mm	10,8	19	ΧI
480 × 400 mm	8,2	22	
480 × 480 mm	9,8	20	WL
480 × 640 mm	13,0	17]
640 × 400 mm	10,8	19	WK
640 × 480 mm	13,0	17	
640 × 640 mm	17,4	13	vc
			_ V(

Material specifications

Pallet plate	5 mm ±0,1 steel plate
Frame	Electrically conductive
	UHMW-PĚ

X85P

XH

XF

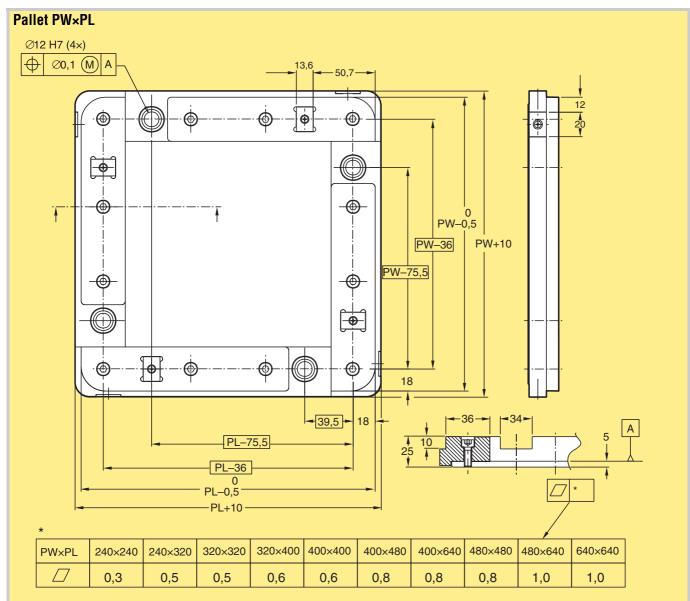
XD

ELV

CTL **FST**

TR

APX



Pallet PW × PL mm

XTPP PW×PL

When ordering, insert the pallet width and the pallet length instead of PWxPL in the designation.

Frame section kit

iaine section kit	
Frame section kit 240 mm	5056945
Frame section kit 320 mm	5056950
Frame section kit 400 mm	5056938
Frame section kit 480 mm	5056940
Frame section kit 640 mm	5056952



Each kit contains two frame pieces, six bushings and four initiation plates with screws. The frames and bushings are suitable for screws type MC6S M6×16 (not included). Two kits are required for each pallet. For use as spare parts and for building non-standard pallets in combination with customer supplied pallet plates.

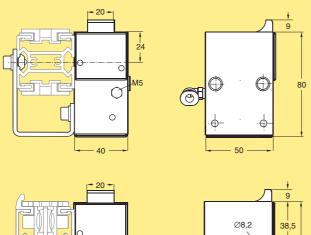
Bushing kit Four bushings

5056944



For building non-standard pallets in combination with customer supplied pallet plates. The bushings are designed for plate thickness 5 mm and should be press-fitted into \emptyset 16 mm holes.

Pallet stop device U200



Pneumatic stopper, 0-200 kg

XTPD U200

Pressure range: Treated compressed air: 4-8 bar Air connection: 6 mm outside diameter tubing Separating function:

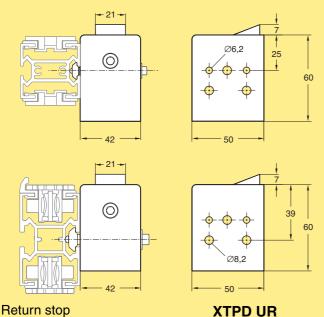
Open: pneumatically. Close: spring-loaded. Mounting hardware is included.

Load kg 250 200 150 100 50 0 Speed 0 5 20 30 m/min Maximum load vs. conveyor speed

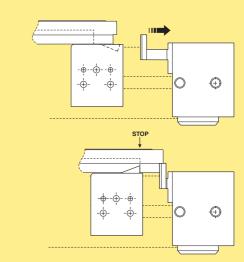
To reduce the noise level, the stopper includes an integrated throttle valve. The throttle setting can be adjusted by means of a screwdriver.

The diagram shows the maximum permissible weight of a group of pallets (product weight + pallet weight), which the stop device is capable of stopping, as a function of the conveyor speed.

Pallet stop device UR



Used in combination with pallet stop devices XTPD U200, D35 or D100.



Stop XTPD UR prevents the pallet from sliding backwards.

The necessary mounting hardware for attachment to an XT or XT Compact conveyor is included in the delivery.

X45

XS X65

X65P

X85

X85P

XΗ XK

XKP

X180

X300

GR

CS

XΤ

WL WK

XC

XF

XD

ELV

CTL

FST

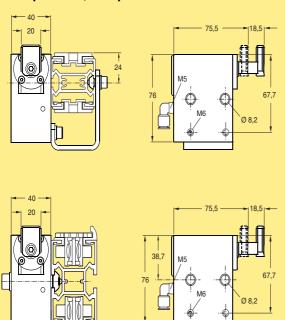
TR

APX

Side support for pallet stop Pallet stop ø6,5 Side support 5055955

The side support is used with pallet sizes larger than 400 mm × 400 mm to minimize the transverse force on the side guide. Hardware for attachment to the conveyor is included in the delivery.

Pallet stop device, damped



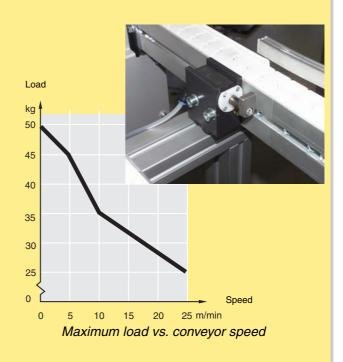
Damped stopper, 0-35 kg

XTPD D35

Pressure range: Treated compressed air: 4–8 bar Air connection: 6 mm outside diameter tubing Separating function:

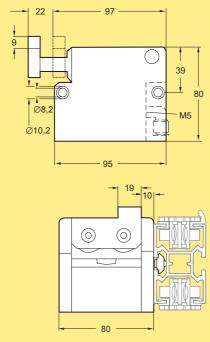
Open: pneumatically. Close: spring-loaded

Mounting hardware is included.



To reduce the noise level, throttle valves should be used (M5). These are not included. The diagram shows the maximum permissible weight of a group of pallets (product weight + pallet weight), which the stop device is capable of stopping, as a function of the conveyor speed.

Pallet stop device, damped

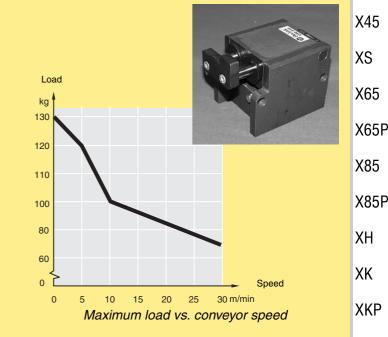


Damped stopper, 0-100 kg

XTPD D100

Pressure range: Treated compressed air: 4–8 bar Air connection: 6 mm outside diameter tubing Separating function:

Separating function:
Open: pneumatically. Close: spring-loaded
Mounting hardware is included.



To reduce the noise level, throttle valves should be used (M5). These are not included. The diagram shows the maximum permissible weight of a group of pallets (product weight + pallet weight), which the stop device is capable of stopping, as a function of the conveyor speed.

GR

X180

X300

CS

ΧT

WL

WK

XC

XF

XD

ELV

CTL

FST

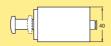
TR

APX

Damper, parallel to main

XT Compact conveyor beam

XT conveyor beam

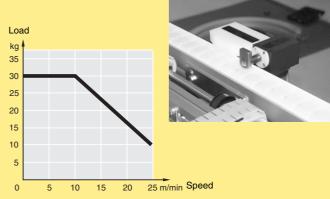


Damper, 0-30 kg

XTPA CM35

Note

The damper is easily influenced by pressure from other pneumatic equipment. To avoid this interference the damper must be connected to a separate pneumatic valve.



Maximum load vs. conveyor speed

The diagram shows the maximum permissible weight of a group of pallets (product weight + pallet weight), which the damper is capable of stopping, as a function of the conveyor speed.

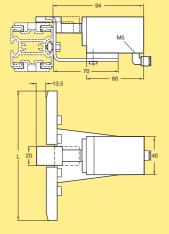
The pneumatic damper XTPA CM35 is used when pallets up to 30 kg have to be damped and transferred from a parallel conveyor to the main conveyor.

Mounting hardware is included in the delivery. Pressure range: Treated compressed air, 4–8 bar Air connection: 6 mm outside diameter tubing Damping function:

Stop in initial position: pneumatically

Damper, main to parallel

XT Compact conveyor beam



Damper, 0–30 kg
PW 240 mm, L=136

PW 320 mm, L=216

PW 400 mm, L=296

PW 480 mm, L=376

PW 640 mm, L=536

XTPA MC35 240 A

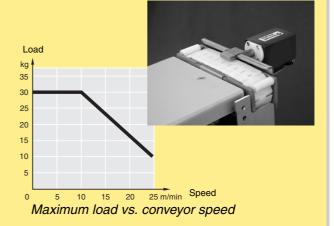
XTPA MC35 320 A

XTPA MC35 400 A

XTPA MC35 480 A

XTPA MC35 640 A

Mounting hardware is included in the delivery.



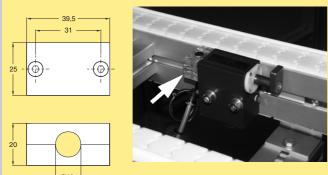
The diagram shows the maximum permissible weight of a group of pallets (product weight + pallet weight), which the damper is capable of stopping, as a function of the conveyor speed.

Pressure range: Treated compressed air, 4–8 bar Air connection: 6 mm outside diameter tubing Damping function: Stop in initial position, pneumatically Note.

The damper is easily influenced by pressure from other pneumatic equipment. To avoid this interference the damper must be connected to a separate pneumatic valve.

Sensor brackets P0

Sensor bracket Type V001



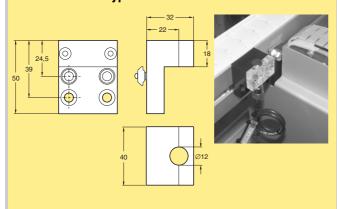
Vertical sensor bracket

XTPB V001

The sensor bracket holds a Ø12 mm vertical sensor and can be mounted on the stopper XTPD U200 and the damped stopper XTPD D35 Mounting hardware is included in the delivery.

Proximity switch is not included.

Sensor bracket Type V002

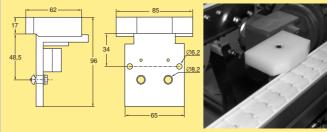


Vertical sensor bracket

XTPB V002

The sensor bracket holds a Ø12 mm vertical sensor and is mounted on the inside of the beam. Mounting hardware is included in the delivery. Proximity switch not included

Sensor bracket Type V003



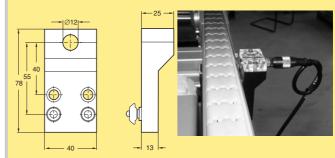
Vertical position sensor bracket

XTPB V003

The position sensor has an increased range and is mounted on the outside of the beam of an XT or XT Compact conveyor. It is intended for use with a Ø 12 mm proximity switch. Mounting hardware is included in the delivery.

Proximity switch is not included.

Sensor bracket Type H001



Horizontal sensor bracket

XTPB H001

The sensor bracket holds a Ø12 mm horizontal proximity switch and is mounted on the outside of the beam of an XT or XT Compact conveyor.

Mounting hardware is included in the delivery.

Proximity sensor is not included.

The horizontal proximity sensor (Ø12 mm) must have a minimum effective sensing distance of 5 mm to the steel initiator plate in the pallet.

Example: The effective sensing distance for SICK (IM12 sensing range 8 mm) is 6,48 mm. This is calculated as follows: 8 mm \times 0,81*.

Useful sensing range = 0,81 × nominal sensing range.

CC

X45

XS

X65

X65P

X85

X85P

XH

XK

XKP

X180

X300

GR

CS

XΤ WL

WK

XC

XF

XD

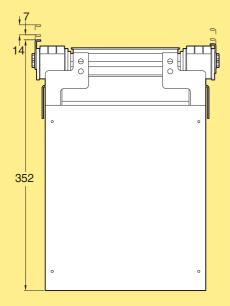
ELV CTL

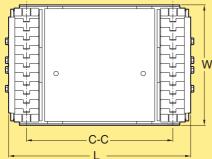
FST

TR

APX

Pneumatic transfer Type M1





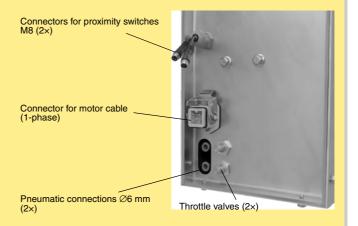
Pneumatic transfer Type M1* Standard chain, 50 Hz Standard chain, 60 Hz Conductive chain, 50 Hz Conductive chain, 60 Hz

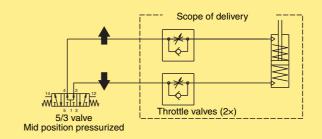
XTPT PW×PL-01 XTPT PW×PL-02 XTPT PW×PL-03 XTPT PW×PL-04

When ordering, insert the pallet size instead of PW×PL in the designation.

*For the following pallet sizes (PW×PL): 240×240: C-C=210, W=169, L=259 240×320: C-C=290, W=169, L=339 320×240: C-C=210, W=249, L=259

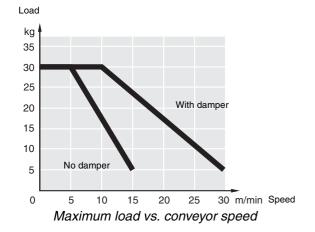
Transfer unit	Туре	240 V 50 Hz motor	115 V 60 Hz motor
XTPT 240×240	M1	S8R25GX-T1	S8R25GE-T1
XTPT 240×320	M1	S8R25GX-T1	S8R25GE-T1
XTPT 320×240	M1	S8R25GX-T1	S8R25GE-T1





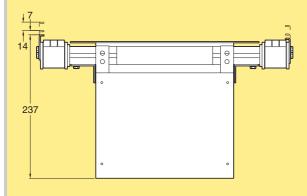
Motor cable connector

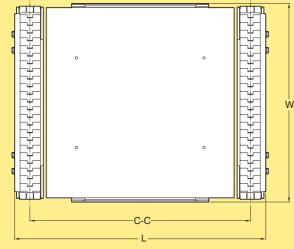
The connector for motor cable is a male 3-pole insert with a housing for the insert. To connect, a female 3-pole insert with a hood for the insert and a screw cap for the hood are required (not supplied by FlexLink). Suitable types are Weidmüller 1498200000 (insert), 1788520000 (hood), and 13-08080521 (M20 screw cap), or equivalent.



The diagram shows the maximum permissible weight of a pallet (product weight + pallet weight), which the transfer is capable of stopping, as a function of the conveyor speed. This diagram applies to transfers type M1, M2 and L.

Pneumatic transfer Type M2





Pneumatic transfer Type M2*

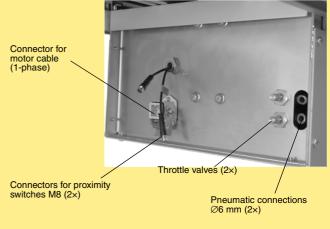
Standard chain, 50 Hz Standard chain, 60 Hz Conductive chain, 50 Hz Conductive chain, 60 Hz

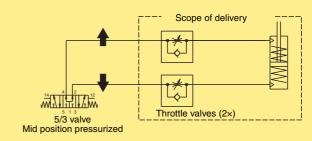
XTPT PW×PL-01 XTPT PW×PL-02 XTPT PW×PL-03 XTPT PW×PL-04

When ordering, insert the pallet size instead of PW×PL in the designation.

*For the following pallet sizes (PW×PL): 320×320: C-C=290, W=249, L=339 320×400: C-C=370, W=249, L=419 400×320: C-C=290, W=329, L=339 400×400: C-C=370, W=329, L=419 400×480: C-C=450, W=329, L=499 400×640: C-C=610, W=329, L=659

Transfer unit	Туре	240 V 50 Hz motor	115 V 60 Hz motor
XTPT 320×320	M2	S9R40GXH-T	S9R40GEH-T
XTPT 320×400	M2	S9R40GXH-T	S9R40GEH-T
XTPT 400×320	M2	S9R40GXH-T	S9R40GEH-T
XTPT 400×400	M2	S9R40GXH-T	S9R40GEH-T
XTPT 400×480	M2	S9R40GXH-T	S9R40GEH-T
XTPT 400×640	M2	S9R40GXH-T	S9R40GEH-T





Motor cable connector

The connector for motor cable is a male 3-pole insert with a housing for the insert. To connect, a female 3-pole XC insert with a hood for the insert and a screw cap for the hood are required (not supplied by FlexLink). Suitable types are Weidmüller 1498200000 (insert), 1788520000 (hood), and 13-08080521 (M20 screw cap), or equiva-

CC

X45

XS

X65

X65P

X85

X85P

XH

XK **XKP**

X180

X300

GR

CS

XΤ

WL

WK

XF

XD

ELV

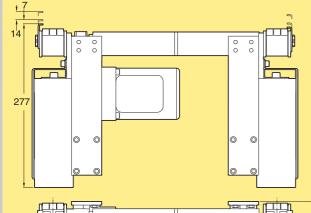
CTL

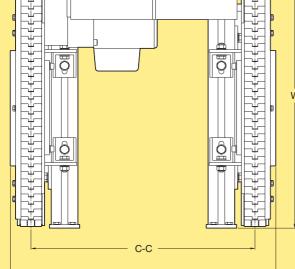
FST

TR

APX

Pneumatic transfer Type L





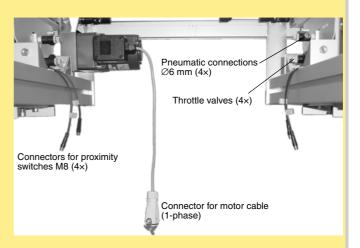
Pneumatic transfer Type L* Standard chain, 50 Hz Standard chain, 60 Hz Conductive chain, 50 Hz Conductive chain, 60 Hz

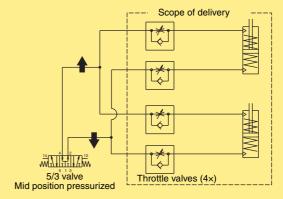
XTPT PW×PL-01 XTPT PW×PL-02 XTPT PW×PL-03 XTPT PW×PL-04

When ordering, insert the pallet size instead of PW×PL in the designation.

*For the following pallet sizes (PW×PL): 480×400: C-C=370, W=405, L=439 480×480: C-C=450, W=405, L=519 480×640: C-C=610, W=405, L=679 640×400: C-C=370, W=565, L=439 640×480: C-C=450, W=565, L=519 640×640: C-C=610, W=565, L=679

Transfer unit	Туре	240 V 50 Hz motor	115 V 60 Hz motor
XTPT 480×400	L	S9R40GXH-T	S9R40GEH-T
XTPT 480×480	L	S9R40GXH-T	S9R40GEH-T
XTPT 480×640	L	S9R40GXH-T	S9R40GEH-T
XTPT 640×400	L	S9R40GXH-T	S9R40GEH-T
XTPT 640×480	L	S9R40GXH-T	S9R40GEH-T
XTPT 640×640	L	S9R40GXH-T	S9R40GEH-T

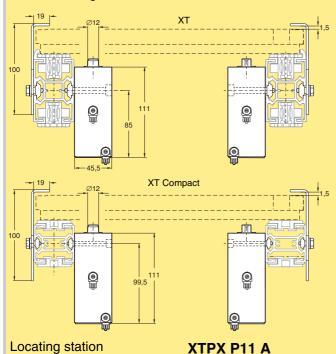




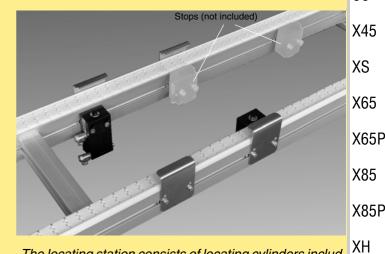
Motor cable connector

The connector for motor cable is a male 3-pole insert with a housing for the insert. To connect, a female 3-pole insert with a hood for the insert and a screw cap for the hood are required (not supplied by FlexLink). Suitable types are Weidmüller 1498200000 (insert), 1788520000 (hood), and 13-08080521 (M20 screw cap), or equivalent.

Pallet locating station



See chapter "Locating function module P11 A", page 349, for information about the locating function module.



The locating station consists of locating cylinders including pins and brackets. Larger pallets may require additional lifting force. A lift unit kit 5055802 is available which contains two lift units without guide pins. Pressure range, treated compressed air: 4–8 bar Air connection: 2×6 mm outside diameter tubing Pallet lifting height: 1,5 mm Maximum vertical force per cylinder at 0,6 MPa: 544 N Throttle valves and the necessary mounting hardware for attachment to an XT or XT Compact conveyor are included.

Lift unit kit



Kit consists of two lift units without guide pins. To be used for large pallets (PW or PL >400 mm). Suitable sensors: SICK, MZT1-03VPS-KR0 magnetic cylinder sensor, DC 3-wire.

GR

XK

XKP

X180

X300

CS

XΤ

WL

WK

XC

XF

XD

ELV

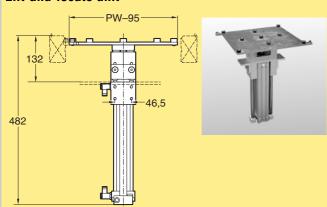
CTL

FST

TR

APX

Lift-and-locate unit



Lift-and-locate unit

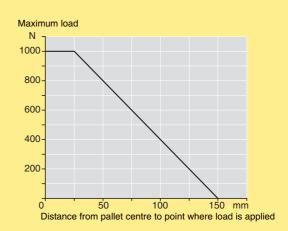
XTPX P12 PW×PL

When ordering, insert the pallet size instead of PW×PL in the designation.

Example: XTPX P12 320×320.

This product is available for all XT pallet sizes. For more information, see "Lift-and-locate function module" on page 351.

Two types of support frame are available, S20 and S21, for different mounting options.



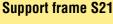
The lift-and-locate unit consists of a plate which can be elevated by a pneumatic cylinder. The plate has two locating pins. The unit can be delivered with top plates adapted for the 15 standard pallet sizes.

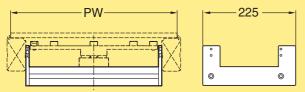
Maximum lift force at centre (0,6 MPa): 1177 N

Lift height: 0-225 mm (adjustable)

Locating repeatability in x and y directions: ±0,05 mm Note (applies to option F01). In order to avoid influence from conveyor movements, attach the conveyor to a reference support.

It is recommended to enclose the unit to protect persons from the clamp risk.



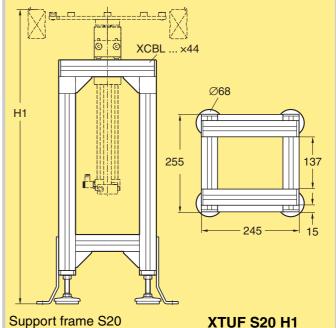


Support frame S21

XTUF S21 PW

When ordering, insert the pallet width instead of PW in the designation. Example: XTUF S21 320.

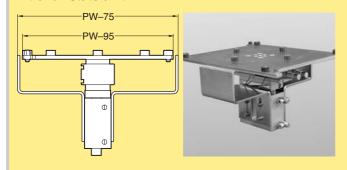
Support frame S20



When ordering, insert chain surface height above floor level instead of H1 in the designation.

Example: XTUF S20 570.

Lift-and-rotate unit



Lift-and-rotate unit

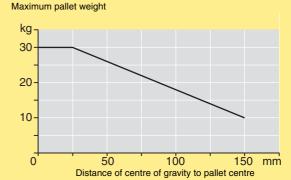
XTPR PW×PL

When ordering, insert the pallet size instead of PW×PL in the designation.

Example: XTPR 320×320.

This product is available for PW and PL dimensions up to and including 400 mm.

For more information, see "Lift-and-rotate function module" on page 351.



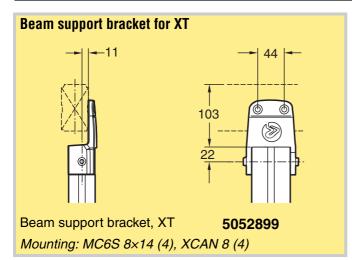
The lift-and-rotate unit consists of a plate which can be elevated and rotated 180°. The plate has two locating pins. The unit is mounted in the T-slots on the inner side of the conveyor beams.

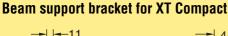
The lift-and-rotate unit is available with top plate adapted for seven standard pallet sizes up to 400 mm x

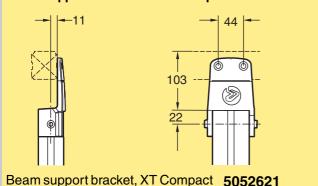
Maximum centered lift force (0,6 MPa): 340 N Maximum mass-moment of inertia: 0,55 kgm²

Rotate angle: 180°. Lift height: 17 mm Weight: 13,2 kg

Support brackets

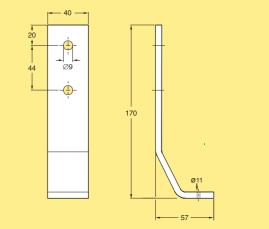






Mounting: ISO 4762 M6x 10 St 8.8 (2), XFAN 6 (2), MC6S 8×14 (2), XCAN 8 (2)

Floor attachment bracket



Floor attachment bracket

XCFA 170 S

The bracket is delivered with the hardware necessary for attachment to the conveyor support. Fasteners for connection to the floor are not supplied with the brack-

XS

P0

CC

X45

X65

X65P

X85

X85P

XΗ

XK **XKP**

X180

X300

CS

GR

WL

WK XC

XF

XD

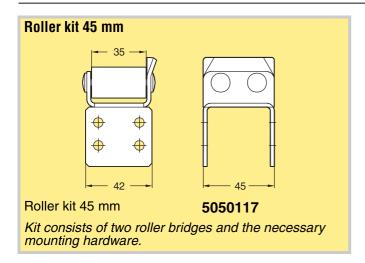
ELV

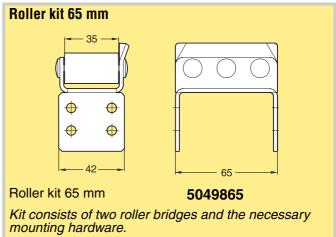
CTL **FST**

TR

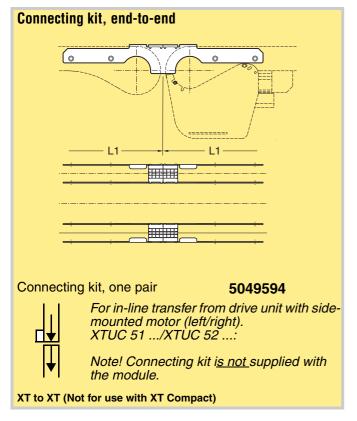
APX

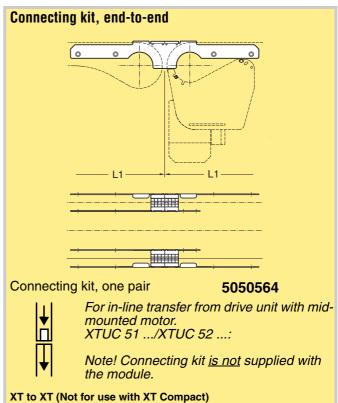
Roller kits

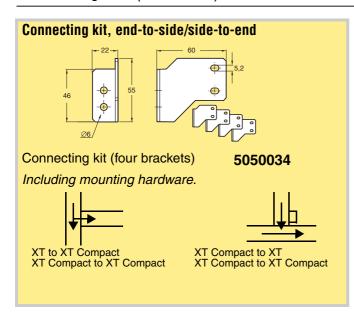


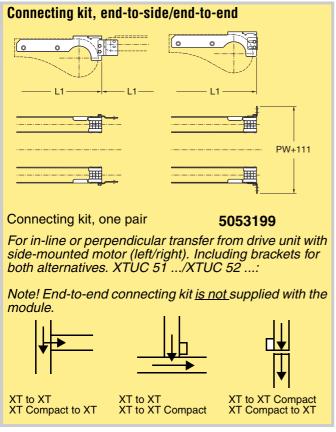


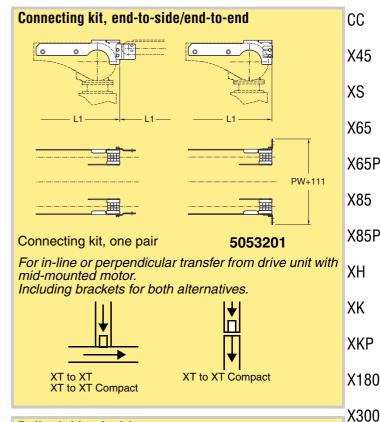
Connecting kits

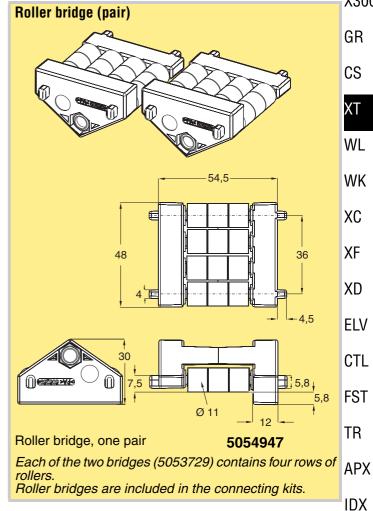




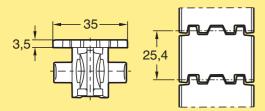








Plain chain, XT



Plain chain, length 5 m Pitch 25,4 mm

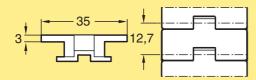
Standard chain (POM B)
Standard link kit **
Conductive chain (POM B COND)
Conductive link kit **

XTTP 5 5056659 XTTP 5 EC 5056660

*Use with conductive slide rail.

**Link kit contains 10 links, 10 pivots, 10 steel pins

Plain chain, XT Compact



Plain chain, XT Compact Pitch 12,7 mm. Only for straight-running conveyor (XT Compact).

Length 3 m

Standard chain (POM B)
Standard link kit **
Conductive chain (POM B COND)*
Conductive link kit **
ISD chain (POM B ISD NAT)*
ISD link kit **
5045028
5056662
5056664
5056664
5056664

*Use with conductive slide rail.

**Link kit contains 10 links, 10 pivots, 10 steel pins

Pin insertion tool for chain





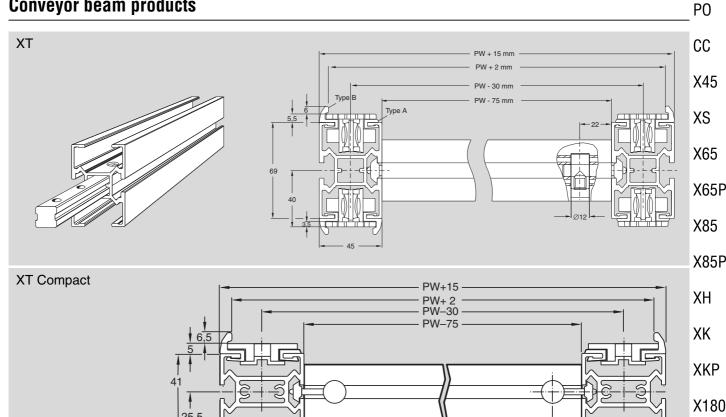
Pin insertion tool

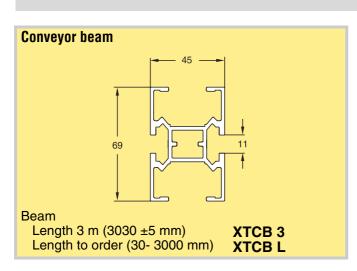
XS-X65-XT XS-X65-XT, PRO version* XLMJ 4 XLMJ 4 P

For FlexLink's XT chains XTTP 5, XTTP 5 EC and 6045771.

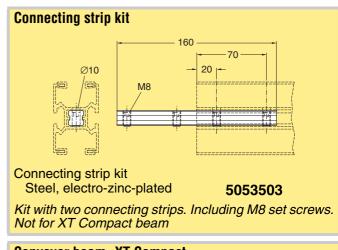
*This product is recommended for frequent users.

Conveyor beam products

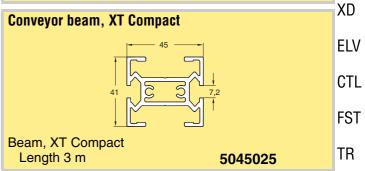




45



20



APX

X300

GR

CS

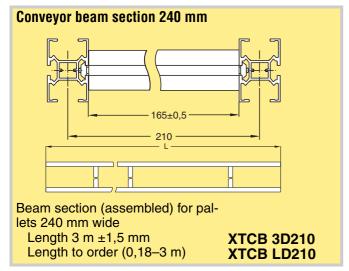
WL

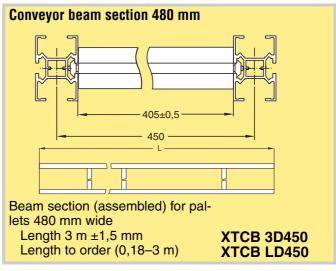
WK

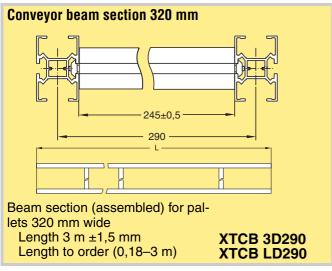
XC

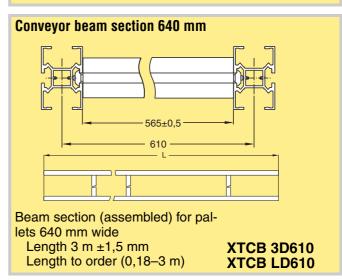
XF

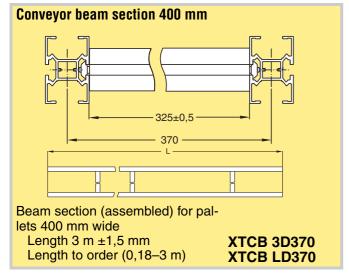
Conveyor beam products (continued)











CC

X45

XS

X65

X65P

X85

X85P

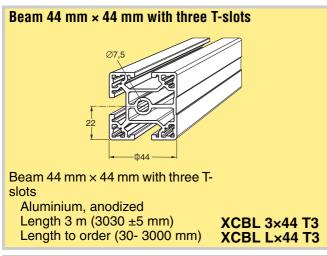
XH

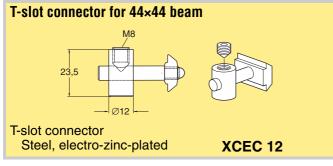
XK

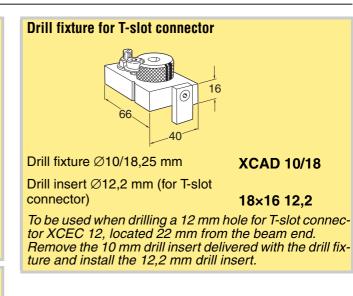
XKP

X180

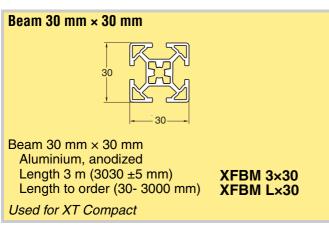
X300

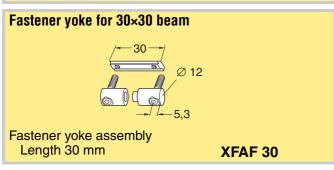


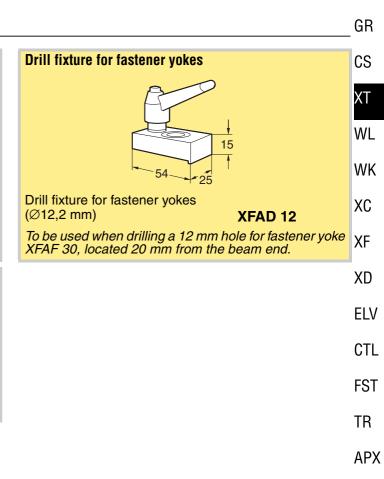




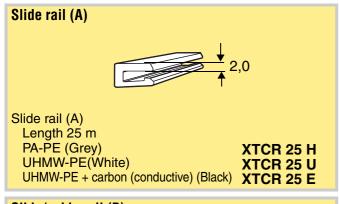
Tools and accessories, 30×30 beam

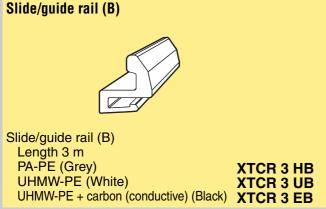


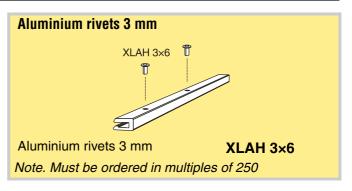




Slide rails







More information

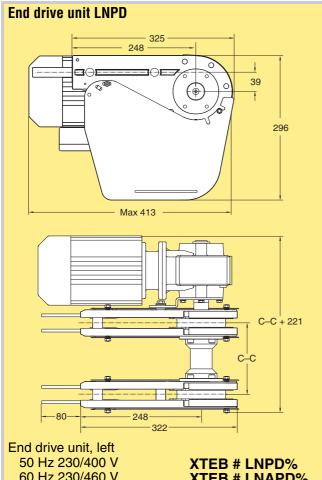
For more information about slide rails, see separate document "XT slide rail instruction".

Slide rail tools





End drive units P0



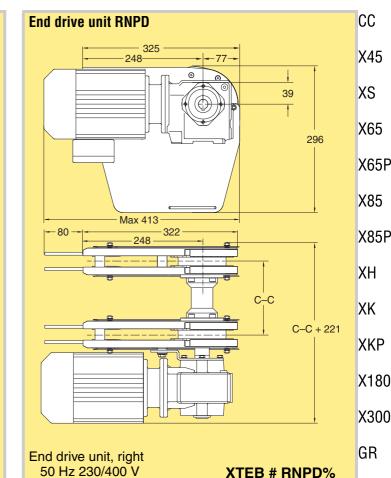
60 Hz 230/460 V **XTEB # LNAPD%**

For PW 240, 320, 400, 480, 640 mm. Insert desired C-C value instead of % in the designa-

tion. C-C=PW-30. Insert desired speed instead of # in the designation:

50 Hz: 5-10-15-20 m/min. 60 Hz: 6-10-16-20 m/min. Connecting strips are included.

Maximum traction force: 1250 N at 5 m/min. Designation example: XTEB 15 LNPD370 is a 50 Hz drive unit for 400 mm wide pallets running at 15 m/min.



For PW 240, 320, 400, 480, 640 mm.

Insert desired C-C value instead of % in the designation. C-C=PW-30.

XTEB # RNAPD%

CS

XΤ

WL

WK

XC

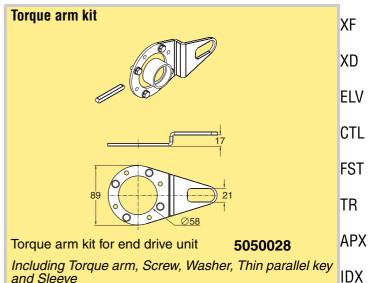
Insert desired speed instead of # in the designation:

50 Hz: 5-10-15-20 m/min. 60 Hz: 6-10-16-20 m/min. Connecting strips are included.

60 Hz 230/460 V

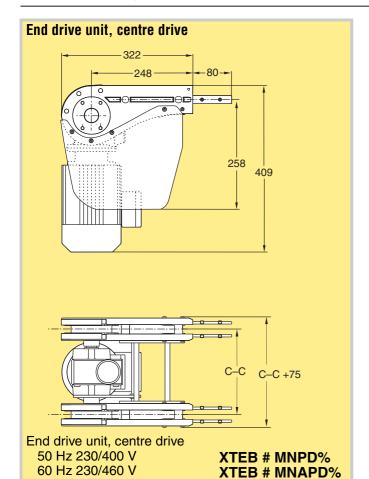
Maximum traction force: 1250 N at 5 m/min.

Designation example: XTEB 20 RNAPD450 is a 60 Hz drive unit for 480 mm wide pallets running at 20 m/min.



and Sleeve

End drive units, centre drive



For PW 240, 320, 400, 480, 640 mm.

Insert desired C-C value instead of % in the designation. C-C=PW-30.

Insert desired speed instead of # in the designation:

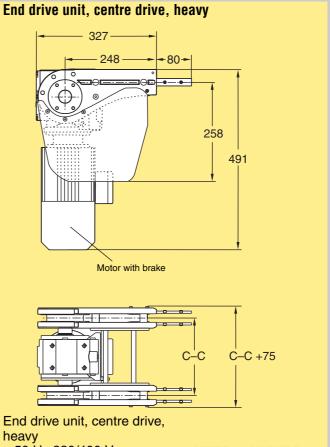
50 Hz: 5-10-15-20 m/min. 60 Hz: 6-10-16-20 m/min.

Connecting strips are included.

Maximum traction force: 1250 N at 5 m/min.

Designation example: XTEB 10 MNPD290 is a 50 Hz

drive unit for 320 mm wide pallets running at 10 m/min.



50 Hz 230/400 V **XTEB # HMNPD%** 60 Hz 230/460 V **XTEB # HMNAPD%**

For PW 240, 320, 400, 480, 640 mm.

Insert desired C-C value instead of % in the designation. C-C=PW-30.

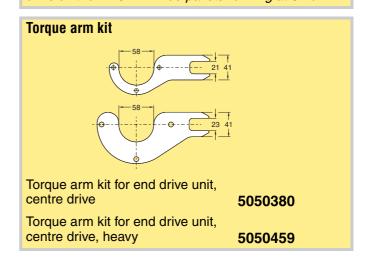
Insert desired speed instead of # in the designation:

50 Hz: 5-10-15 m/min. 60 Hz: 6-10-16 m/min.

Connecting strips are included.

Maximum traction force: 1800 N at 5 m/min.

Designation example: XTEB 6 HMNAPD210 is a 60 Hz drive unit for 240 mm wide pallets running at 6 m/min.



X300

GR

CS

XΤ

WL

WK

XC

XF

XD

ELV

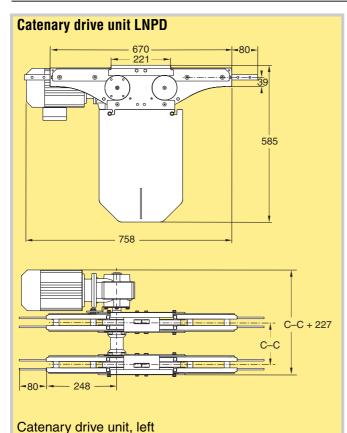
CTL

FST

TR

APX

IDX



50 Hz 230/400 V

XTEC # LNPD% 60 Hz 230/460 V **XTEC # LNAPD%**

For PW 240, 320, 400, 480, 640 mm.

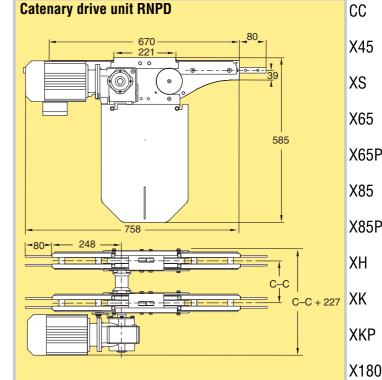
Insert desired C-C value instead of % in the designation. C-C=PW-30.

Insert desired speed instead of # in the designation:

50 Hz: 5-10-15-20 m/min. 60 Hz: 6-10-16-20 m/min.

Connecting strips are included.

Maximum traction force: 1250 N at 5 m/min. Designation example: XTEC 6 LNAPD610 is a 60 Hz drive unit for 640 mm wide pallets running at 6 m/min.



Catenary drive unit, right

50 Hz 230/400 V **XTEC # RNPD%** 60 Hz 230/460 V **XTEC # RNAPD%**

For PW 240, 320, 400, 480, 640 mm.

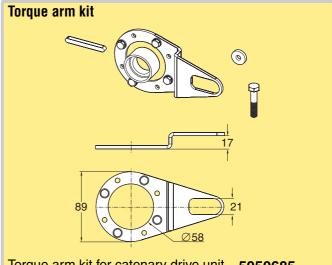
Insert desired C-C value instead of % in the designation. C-C=PW-30.

Insert desired speed instead of # in the designation: 50 Hz: 5-10-15-20 m/min.

60 Hz: 6-10-16-20 m/min.

Connecting strips are included.

Maximum traction force: 1250 N at 5 m/min. Designation example: XTEC 5 RNPD370 is a 50 Hz drive unit for 400 mm wide pallets running at 5 m/min.



Torque arm kit for catenary drive unit 5050685

Including Torque arm, Screw, Washer, Sleeve, Thin parallel key, Screw and Washer M8x40

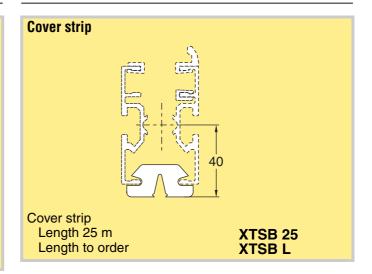
⊘ Flex Link®

Idler end unit

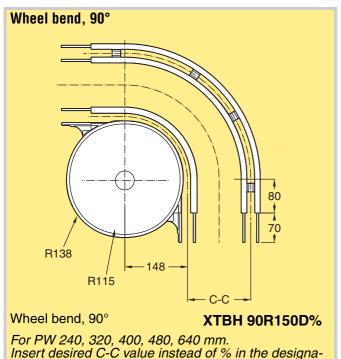
Idler end unit Idler end unit (single) Length 320 mm XTEJ 320 Two idler units must be ordered for a conveyor with return chain. Connecting strips are included.

Cover strip

Wheel bend, 180°



Wheel bends



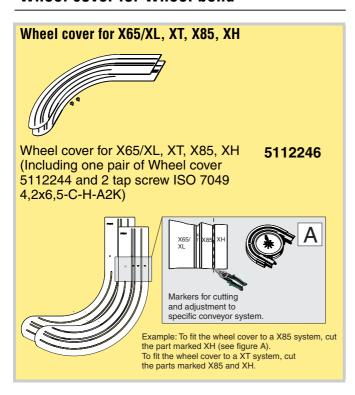
tion. C-C=PW-30.
Connecting strips are included.
Designation example: XTBH 90R150D450 is a 90°

wheel bend for 480 mm wide pallets.

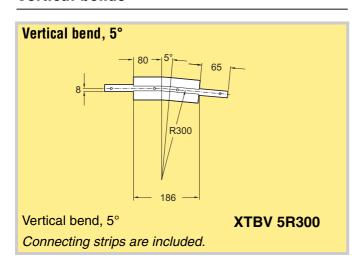
Wheel bend, 180° XTBH180R150D%

For PW 240, 320, 400, 480, 640 mm.
Insert desired C-C value instead of % in the designation. C-C=PW-30.
Connecting strips are included.
Designation example: XTBH 180R150D210 is a 180° wheel bend for 240 mm wide pallets.

Wheel cover for Wheel bend



Vertical bends



P0

CC

X45

XS

X65

X65P

X85

X85P

XH

XK

XKP

X180

X300

GR

CS

XΤ

WL

WK

XC

XF

XD

ELV

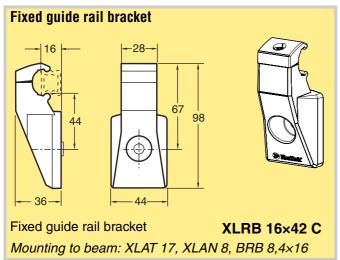
CTL

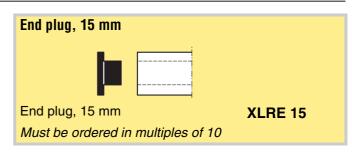
FST

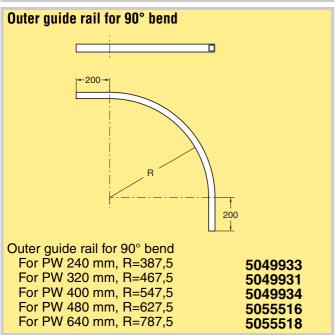
TR

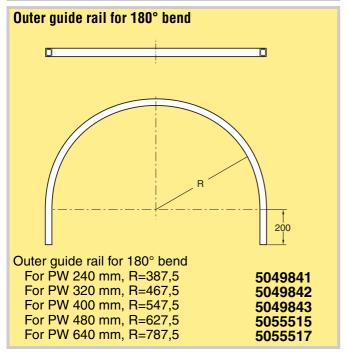
APX

Guide rail components









CC

X45

XS

X65

X65P

X85

X85P

XH

XK

XKP

X180

X300

GR

CS

XΤ

WL

WK

XC

XF

XD

ELV

CTL

FST

TR

APX

