



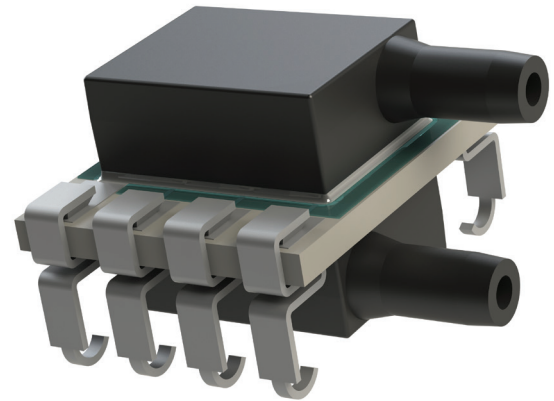
LP Series - Digital is a surface mountable pressure sensor package with a compensated digital output suitable for ultra-low pressure sensing applications.

COMPANY: Merit Sensor is a leader in piezoresistive pressure sensing and partners with clients to create high performing solutions for a variety of applications and industries.

SENTIUM: Merit Sensor products incorporate a proprietary Sentium® technology developed to provide a best-in-class operating temperature range (-40°C to 85°C) and superior stability.

TECHNOLOGY: Merit Sensor utilizes a piezoresistive Wheatstone bridge in a design that anodically bonds glass to a chemically etched silicon diaphragm. All products are RoHS compliant.

CAPABILITIES: Merit Sensor designs, engineers, fabricates, dices, assembles, tests, sells and services die and packaged products from a state-of-the-art facility near Salt Lake City, Utah.



FEATURES

Pressure Range	0.15 to 1 psi (10.3 to 68.9 mbar; 1.03 to 6.89 KPa; 4.2 to 27.7 in H <sub>2</sub> O)
Output	I <sup>2</sup> C
Type	Gage and Differential
Media	Clean, Dry Air and Non-corrosive Gases
Packaging	Tape and Reel
Customization	Sensitivity, Resistance, Bridge, Constraint, etc.

BENEFITS

Performance	Enjoy best-in-class performance due to Merit's proprietary Sentium technology
Cost	Save money over time with high-performing die
Security	Feel confident doing business with an experienced company backed by a solid parent company (NASDAQ: MMSI)
Speed	Get to market quickly with creative and flexible solutions
Service	Experience prompt, personal and professional support

**1420 Family Part Number Configurator**

1420-XXXX-XX11-111

<p><b>Pressure</b></p> <p>P15 = .15psi P30 = .30psi 1P0 = 1.0psi</p>	<p><b>Reference</b></p> <p>D = Differential G = Gage</p>	<p><b>Clock Speed</b></p> <p>1 = 1MHz</p>	<p><b>I<sup>2</sup>C Address</b></p> <p>0 = 0x28 1 = 0x38 2 = 0x48 3 = 0x58 4 = 0x68 5 = 0x78 6 = Open*</p>	<p><b>Pin Type</b></p> <p>1 = J-lead</p>	<p><b>Port</b></p> <p>1 = Dual horizontal, facing same direction</p>	<p><b>Input Buffer</b></p> <p>1 = None</p>	<p><b>Update Rate</b></p> <p>1 = 5ms</p>	<p><b>Operation Mode</b></p> <p>1 = Update mode constant</p>
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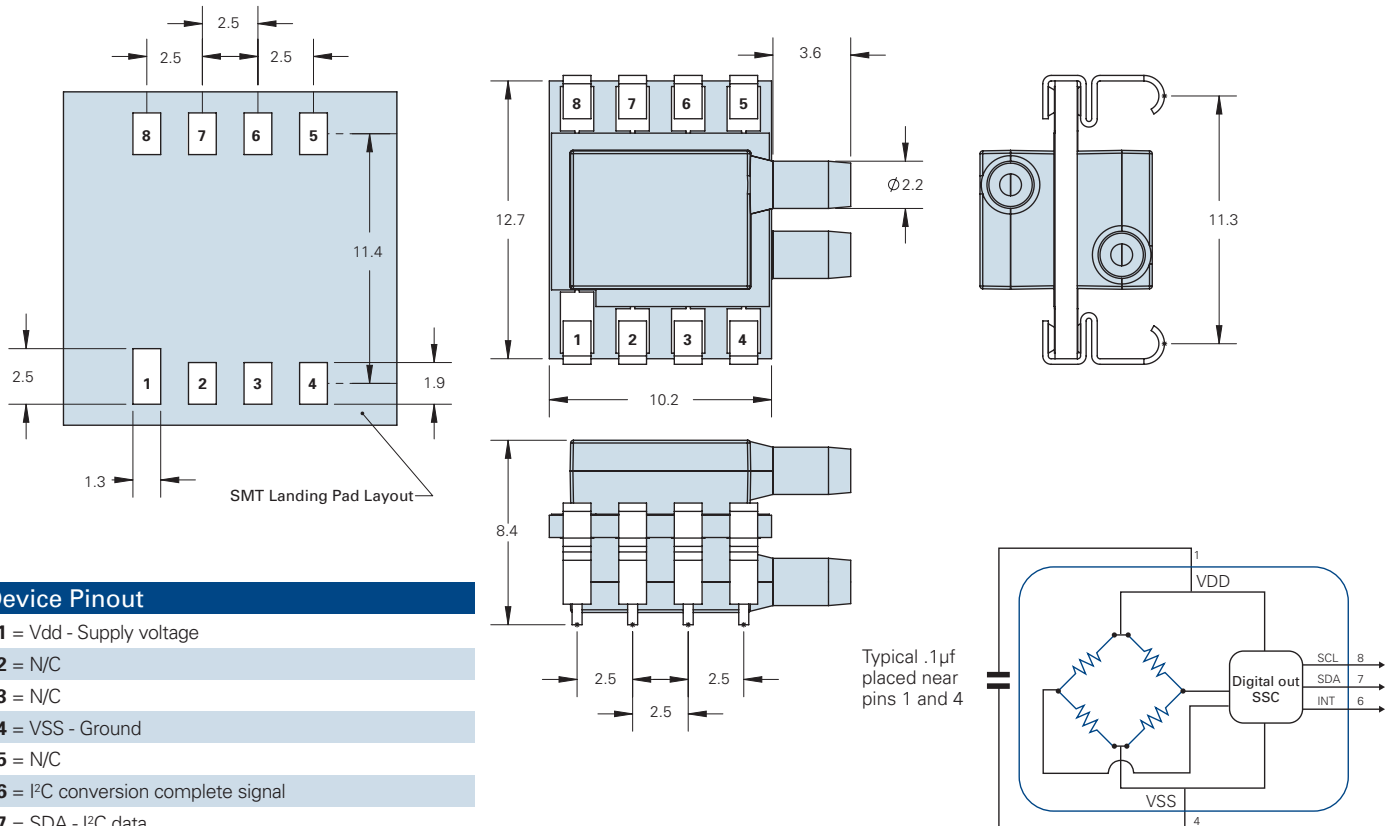
\*Device will respond to any address.

**SPECIFICATIONS**

Parameter	Minimum	Typical	Maximum	Units	Notes
<b>Electrical</b>					
Supply Voltage (Vdd)	4.5	5	5.5	V	
Supply Current		3		mA	(1)
Operating Temperature	-40		85	°C	
Storage Temperature	-55		100	°C	
<b>Performance</b>					
Pressure ADC Resolution			14	Bits	
Pressure Accuracy	-1.5		1.5	% FSO	(2) (3)
Startup time		15		ms	
Digital update time	0.5		125	ms	
Proof Pressure	5X				(4)
Burst Pressure	10 psi				
<b>Transfer Function Formula</b>					
$P_{psi} = (P_{max} - P_{min}) \cdot \left( \frac{P_{counts} - 0.1 \cdot Max}{0.8 \cdot Max} \right) + P_{min}$			<b>Where</b> <i>P<sub>psi</sub></i> = Measured Pressure in PSI <i>P<sub>counts</sub></i> = Pressure Counts from Merit Sensor Part <i>P<sub>Min</sub></i> = Minimum Calibrated Pressure <i>P<sub>Max</sub></i> = Maximum Calibrated Pressure Max = 16384 = 14 Bit Resolution		
<b>Media Compatibility</b>					
For Use With Non-corrosive Dry Gasses					
Solder temperature: max 250 °C, 5 seconds max					

**Notes:**  
 (1) @5V input voltage,  
 (2) Over 0°C to 60°C  
 (3) Applicable if Vdd = 4.75V to 5.25V  
 (4) Full scale pressure

**DIMENSIONS (millimeters)**

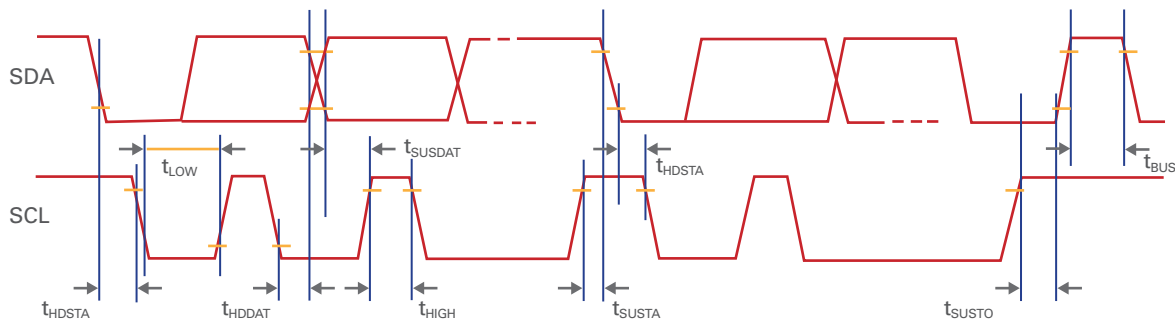


Device Pinout	
<b>P1</b>	= Vdd - Supply voltage
<b>P2</b>	= N/C
<b>P3</b>	= N/C
<b>P4</b>	= VSS - Ground
<b>P5</b>	= N/C
<b>P6</b>	= I <sup>2</sup> C conversion complete signal
<b>P7</b>	= SDA - I <sup>2</sup> C data
<b>P8</b>	= SCL - I <sup>2</sup> C clock

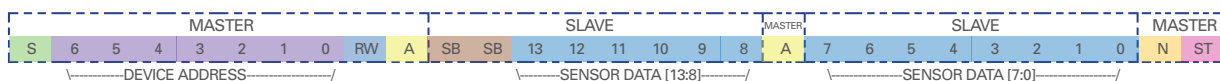
**I<sup>2</sup>C PARAMETERS \***

Parameter	Symbol	Min	Typ	Max	Units
SCL clock frequency	f <sub>SCL</sub>	100		400	kHz
Start condition hold time relative to SCL edge	t <sub>HDSTA</sub>	0.1			μs
Minimum SCL clock low width <sup>1</sup>	t <sub>LOW</sub>	0.6			μs
Minimum SCL clock high width <sup>1</sup>	t <sub>HIGH</sub>	0.6			μs
Start condition setup time relative to SCL edge	t <sub>SUSTA</sub>	0.1			μs
Data hold time on SDA relative to SCL edge	t <sub>HDDAT</sub>	0.0			μs
Data setup time on SDA relative to SCL edge	t <sub>SUDAT</sub>	0.1			μs
Stop condition setup time on SCL	t <sub>SUSTO</sub>	0.1			μs
Bus free time between stop condition and start condition	t <sub>BUS</sub>	2			μs

<sup>1</sup>Combined low and high widths must equal or exceed minimum SCLK period.

**I<sup>2</sup>C TIMING DIAGRAM\***

**MERIT SENSOR 1420 I<sup>2</sup>C COMMUNICATION**

Communications to the 1420 is read only. To read the pressure counts, the master performs a read request by asserting a start condition, sending the 7 bit address of the part (If the part has an open address, 7 bits of anything is acceptable), and sets the read/write bit. The master then waits for an acknowledgment. The acknowledgment is sent by the pressure sensor along with 2 bits of status and bits 13:8 of the pressure counts, the master acknowledges the first 8 bits, and the pressure sensor sends the remaining 8 bits of data. The Master then does not acknowledge and sends a stop condition signaling the end of the transaction.



<b>S</b> Start Conditioning	<b>#</b> Device Slave Address	<b>#</b> Data Bit	<b>Status Bits</b>	
<b>RW</b> Read/Write Bit	<b>A</b> Acknowledge Bit	<b>N</b> No Acknowledge Bit	0 0	Normal Operation, Good Packet
<b>ST</b> Stop Condition	<b>SB</b> Status Bits		0 1	Device in Command Mode
			1 0	Stale Data
			1 1	Diagnostic Condition Exists

\*Used by permission, ZMDI

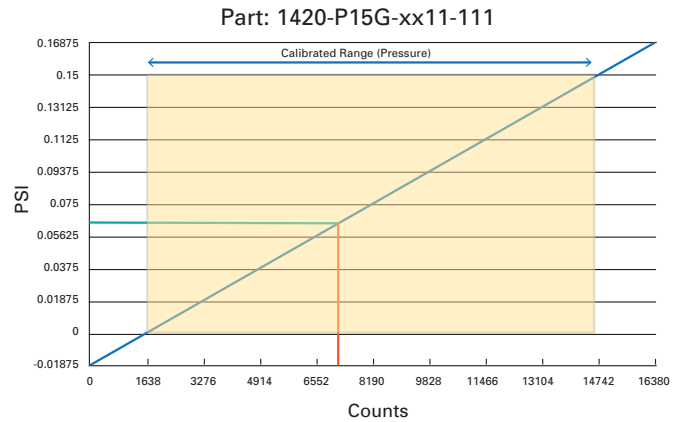
**TRANSFER FUNCTION EXAMPLES**
**Example 1: 0.15 PSI Gage**

Part: 1420-P15G-xx11-111

 $P_{min} = 0.0 \text{ PSI}$ 
 $P_{max} = 0.15 \text{ PSI}$ 
 $P_{counts} = 7215$ 
 $Max = 16384$ 

$$P_{psi} = (P_{max} - P_{min}) \cdot \left( \frac{P_{counts} - 0.1 \cdot Max}{0.8 \cdot Max} \right) + P_{min}$$

$$P_{Psi} = (0.15 - 0.0) \cdot \left( \frac{7215 - 0.1 \cdot 16384}{0.8 \cdot 16384} \right) + 0$$

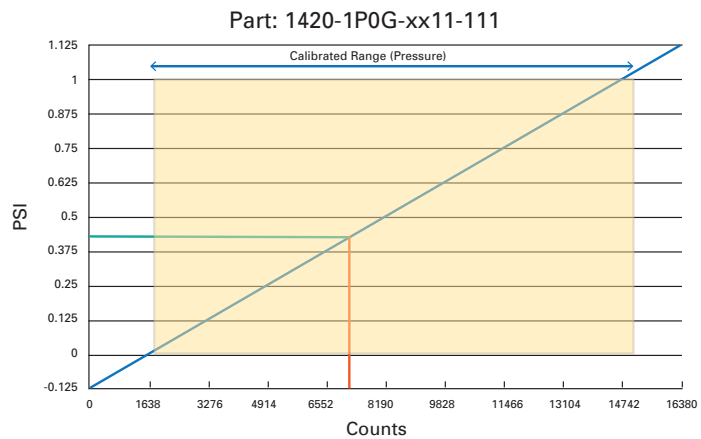
 $P_{Psi} = .0638 \text{ Psi}$ 

**Example 2: 1.0 PSI Gage**

Part: 1420-1P0G-xx11-111

 $P_{min} = 0.0 \text{ PSI}$ 
 $P_{max} = 1.0 \text{ PSI}$ 
 $P_{counts} = 7215$ 
 $Max = 16384$ 

$$P_{psi} = (P_{max} - P_{min}) \cdot \left( \frac{P_{counts} - 0.1 \cdot Max}{0.8 \cdot Max} \right) + P_{min}$$

$$P_{Psi} = (1 - 0.0) \cdot \left( \frac{7215 - 0.1 \cdot 16384}{0.8 \cdot 16384} \right) + 0$$

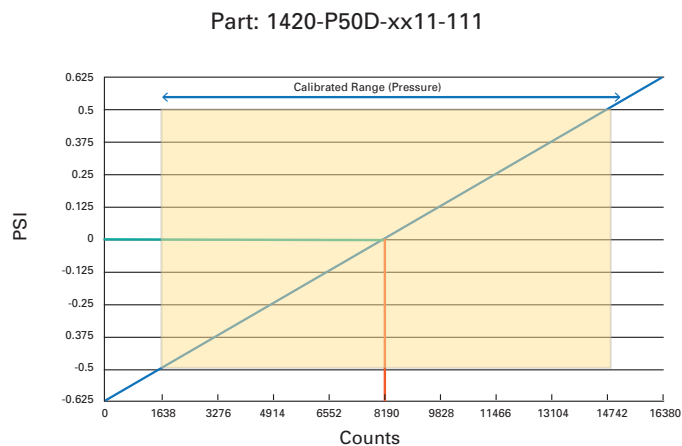
 $P_{Psi} = .4255 \text{ Psi}$ 

**Example 3: -.5 to .5 PSI Differential**

Part: 1420-P50D-xx11-111

 $P_{min} = -0.5 \text{ PSI}$ 
 $P_{max} = 0.5 \text{ PSI}$ 
 $P_{counts} = 8192$ 
 $Max = 16384$ 

$$P_{psi} = (P_{max} - P_{min}) \cdot \left( \frac{P_{counts} - 0.1 \cdot Max}{0.8 \cdot Max} \right) + P_{min}$$

$$P_{Psi} = (0.5 - (-0.5)) \cdot \left( \frac{8192 - 0.1 \cdot 16384}{0.8 \cdot 16384} \right) + (-0.5)$$

 $P_{Psi} = 0.0 \text{ Psi}$ 


# Mouser Electronics

Authorized Distributor

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Merit Sensor:

[1420-P15D-1611-111](#) [1420-P15G-1611-111](#)